

# Systems Digitalization: Start integrated, stay integrated!

Model Based Systems Engineering

We are

# Siemens Digital Industries Software



## Introductions

**SIEMENS**  
*Ingenuity for life*



Piet van Dongen



Stefan Hovens



Marco Peters



# Agenda



- Introduction
- Vision Siemens Digital Industries Software (Piet)
- Digitalization of Systems Engineering (Stefan)
- Requirement Management with Polarion (Marco)



**1847**

A small garage  
startup in Berlin,  
Germany

Employees

**10**

---

Start-up capital

**6.842**

thalers

---

1<sup>st</sup> year revenue

**3,420**

thalers

---





**SIEMENS**  
*Ingenuity for life*

**Today**

Leading position in  
Electrification, Automation  
and Digitalization.

Employees

**377,000+**

Revenue

**€82.9 billion**

Net Income<sup>1</sup>

**€6.1 billion**

Profit margin Ind. Business

**11.2%**

Key figures as of Oct 2017 1 Strategic Unit

# Siemens at a glance



## Operating Companies



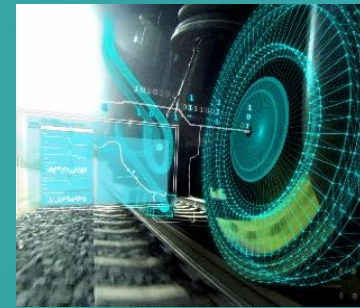
Gas and Power



Smart Infrastructure



Digital Industries



Mobility



SIEMENS Gamesa  
RENEWABLE ENERGY



SIEMENS Healthineers

## Service Companies

Financial Services

Global Business Services

Real Estate Services



We are

# Siemens Digital Industries Software



Business Unit of Siemens Digital Industries

Workforce: 22,000+

Locations: 250 in 36 countries

Customers: 170,000+

## Organization

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Product Lifecycle Management

Electronic Design Automation

Manufacturing Operations Management

Performance Analytics Software

Rapid Application Development tools and Services

## Products

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# Focus on Industry



## Siemens Digital Industries Software Industry Sectors

Aerospace  
and Defense



Automotive  
and  
Transportation



Electronics



Semiconductors



Consumer  
Products  
and Retail



Energy  
and Utilities



Industrial  
Machinery  
and Heavy  
Equipment



Marine



Medical Devices  
and  
Pharmaceuticals





# Agenda

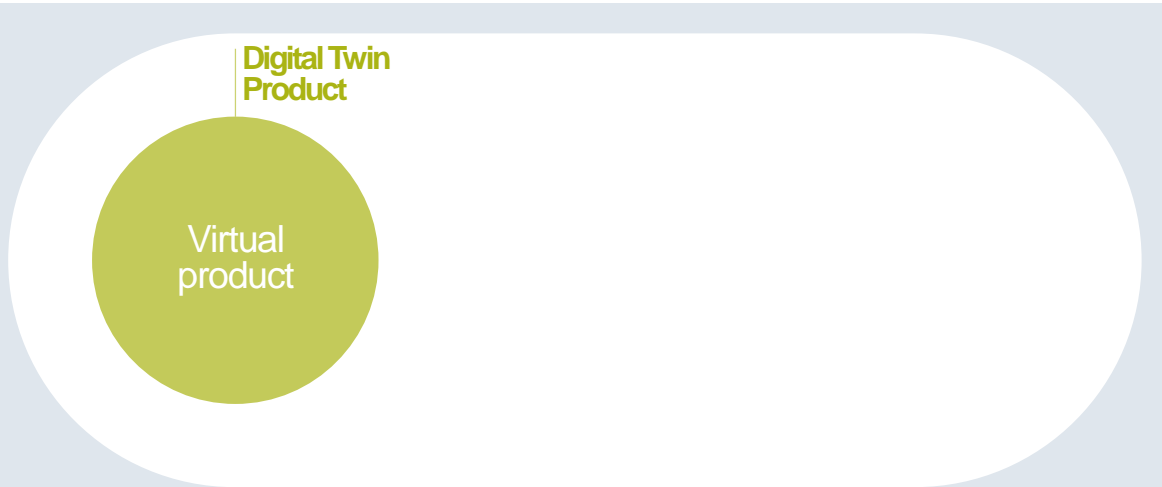


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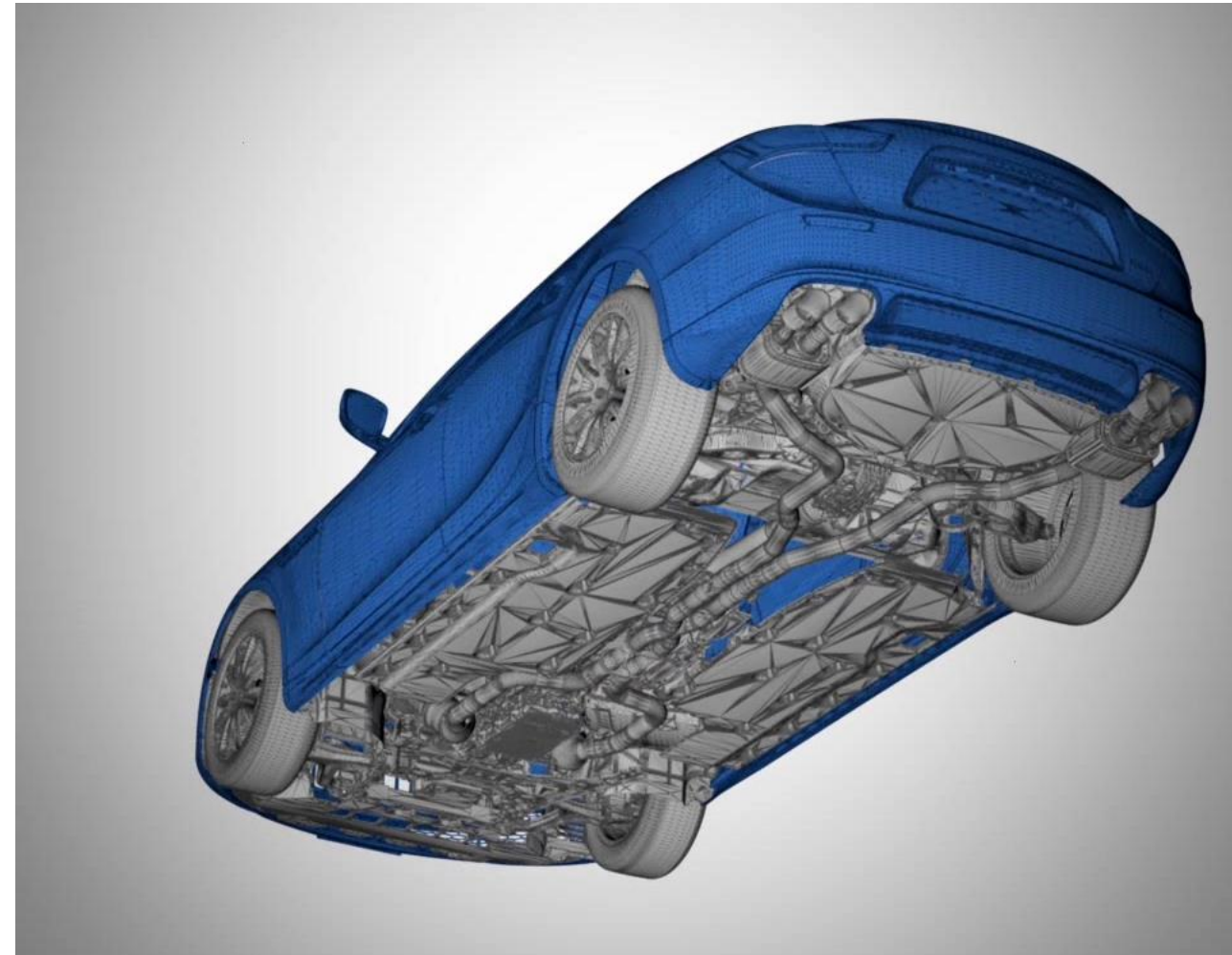




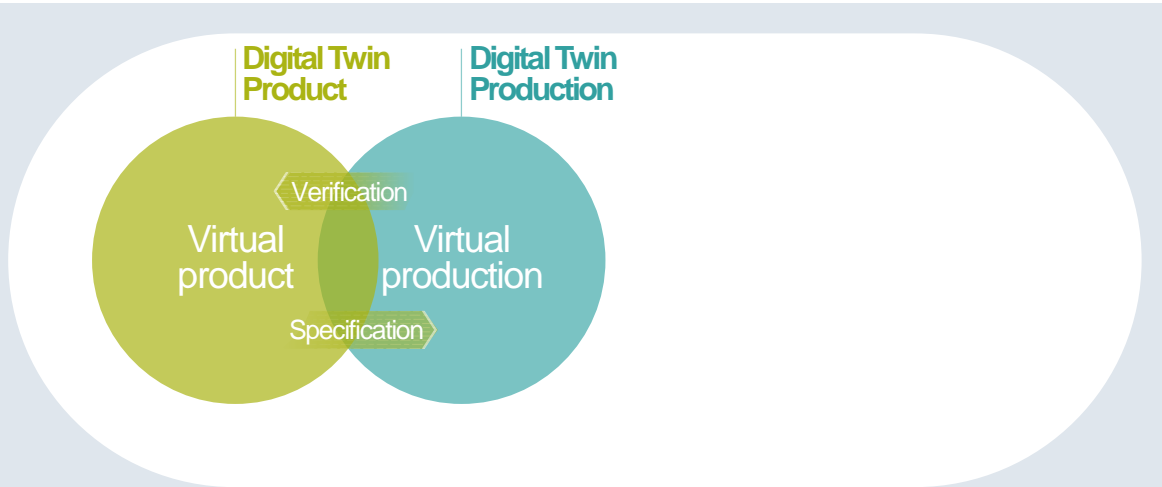
# Digital Twin Product



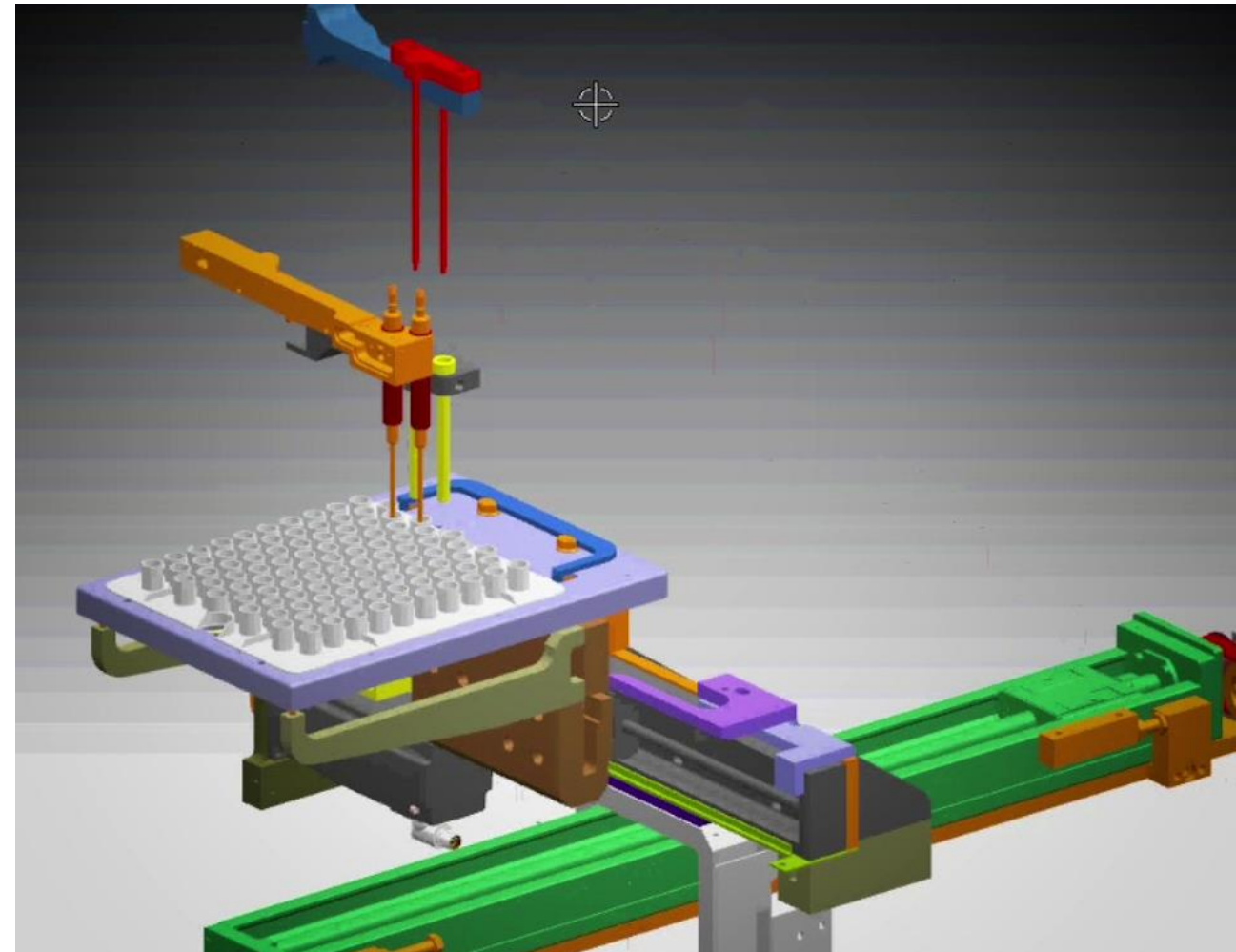
**Design, simulate and verify products digitally, including mechanics and multi-physics, electronics and management of software**



# Digital Twin Production

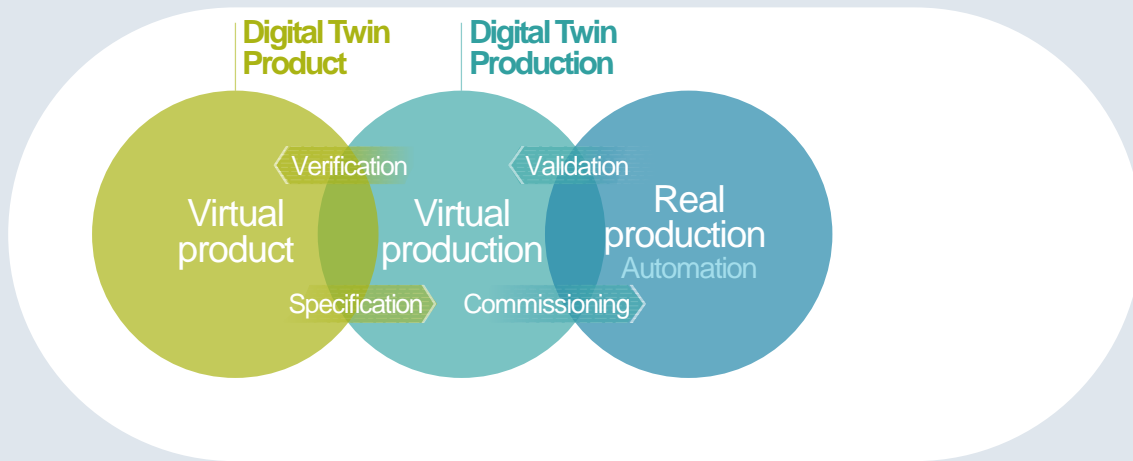


**Plan, simulate and optimize production digitally with PLC code generation and virtual commissioning.**





## Real production

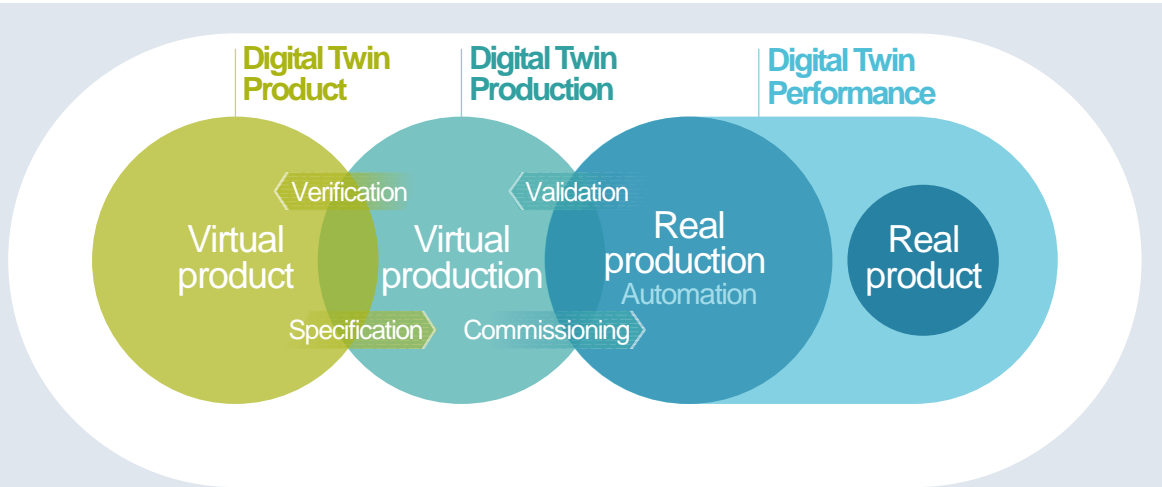


**Execute production, run quality inspections, schedule and process work operations**

**Run production efficiently and securely with Totally Integrated Automation**



# Digital Twin Performance

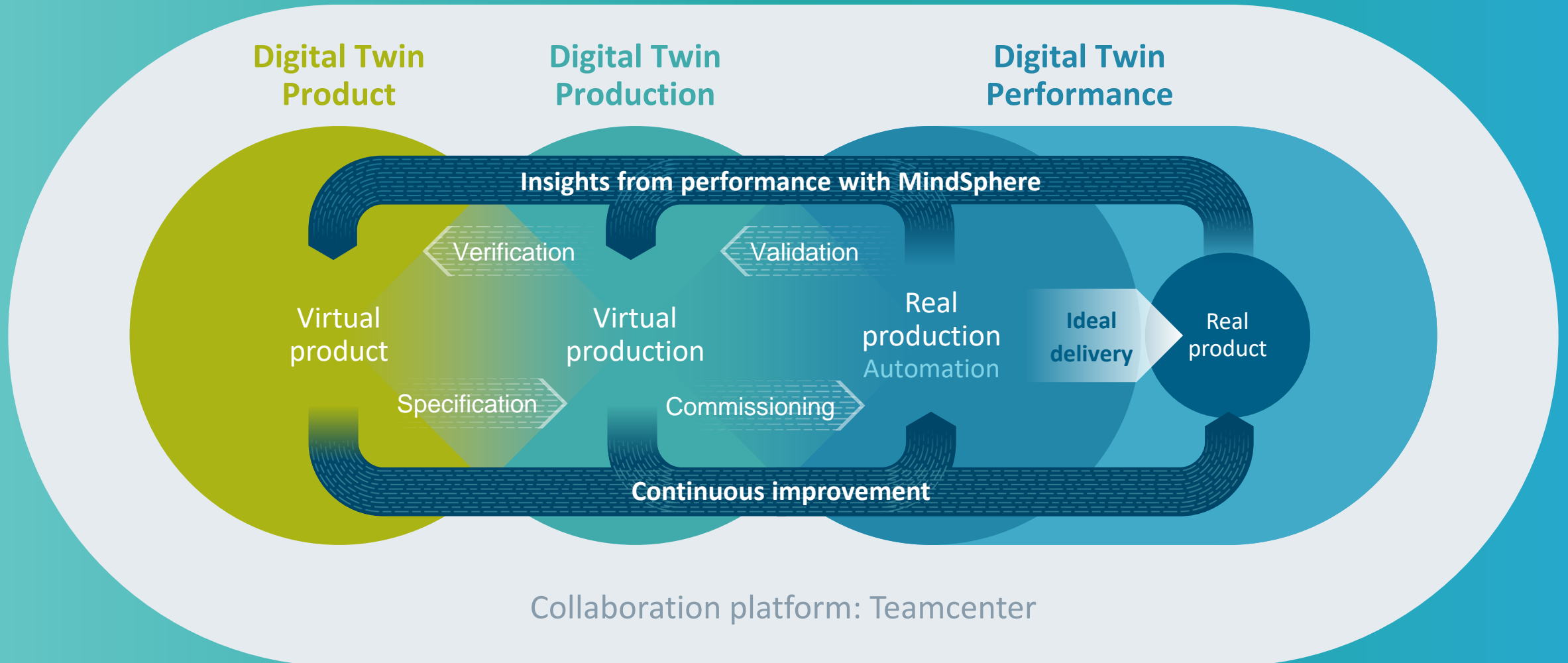


**Analyze and evaluate product and production performance**

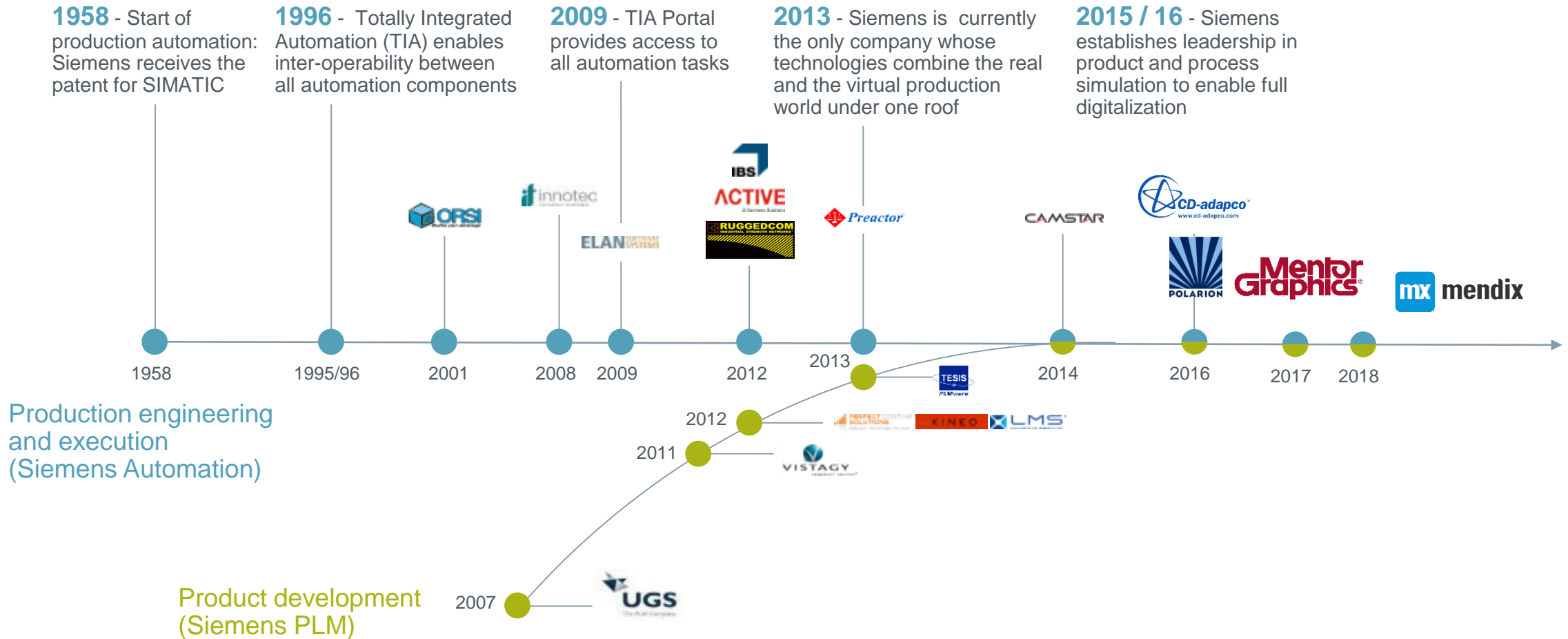




# Proven examples of Customer Value



# Siemens continuously invests in the future ...which is increasingly Digital





**EXPERIENCE**  
APPLICATIONS

# Siemens Cloud Solutions

**CONNECT**

BUSINESS INSIGHTS  
AND NEW CUSTOMERS

**MindSphere**

**ACCESS**

DOMAIN EXPERTISE

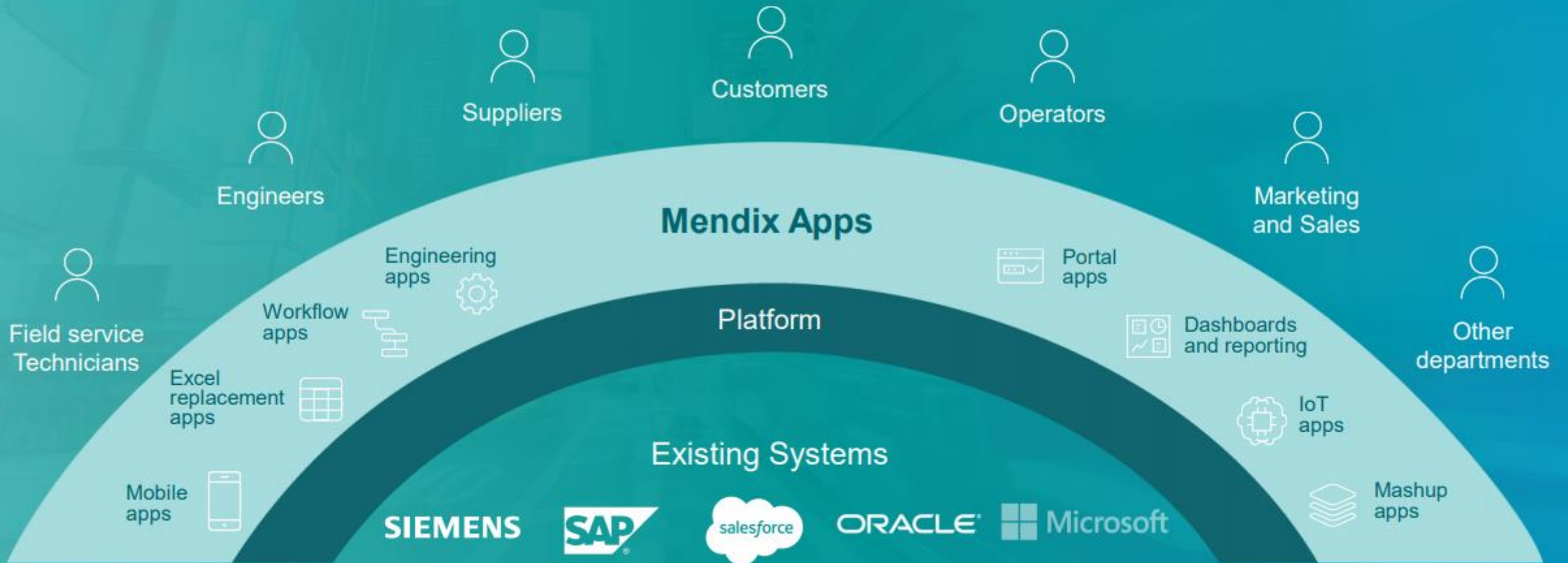
**BUILD - INTEGRATE -  
EXTEND**

RAPID APPLICATION  
DEVELOPMENT

**mx mendix**

# Accelerate Innovation in the Cloud

Unlock and Extend *any* existing data or system



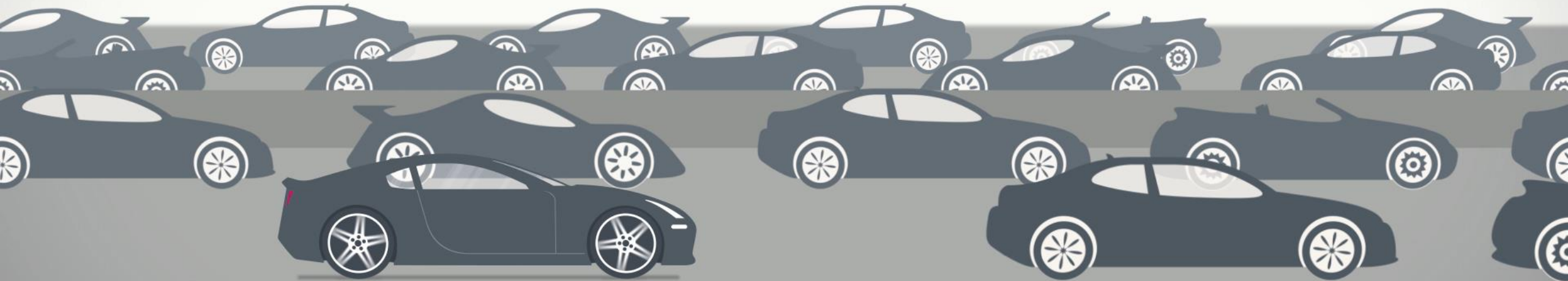


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# Teamcenter integrated multi-domain system modeling







**INCOSE** defines **MBSE** as


“Model-based systems engineering (**MBSE**) is the formalized application of modeling to support **system** requirements, design, analysis, verification and validation activities beginning in the **conceptual design phase** and continuing throughout development and later life cycle phases. ”May 17, 2019

# Comprehensive Product Digital Twin


 What function am I performing?


 How might it fail?


 How do we test it?


 Does anything interfere?

 Why was this decision made?

 What will it look like?

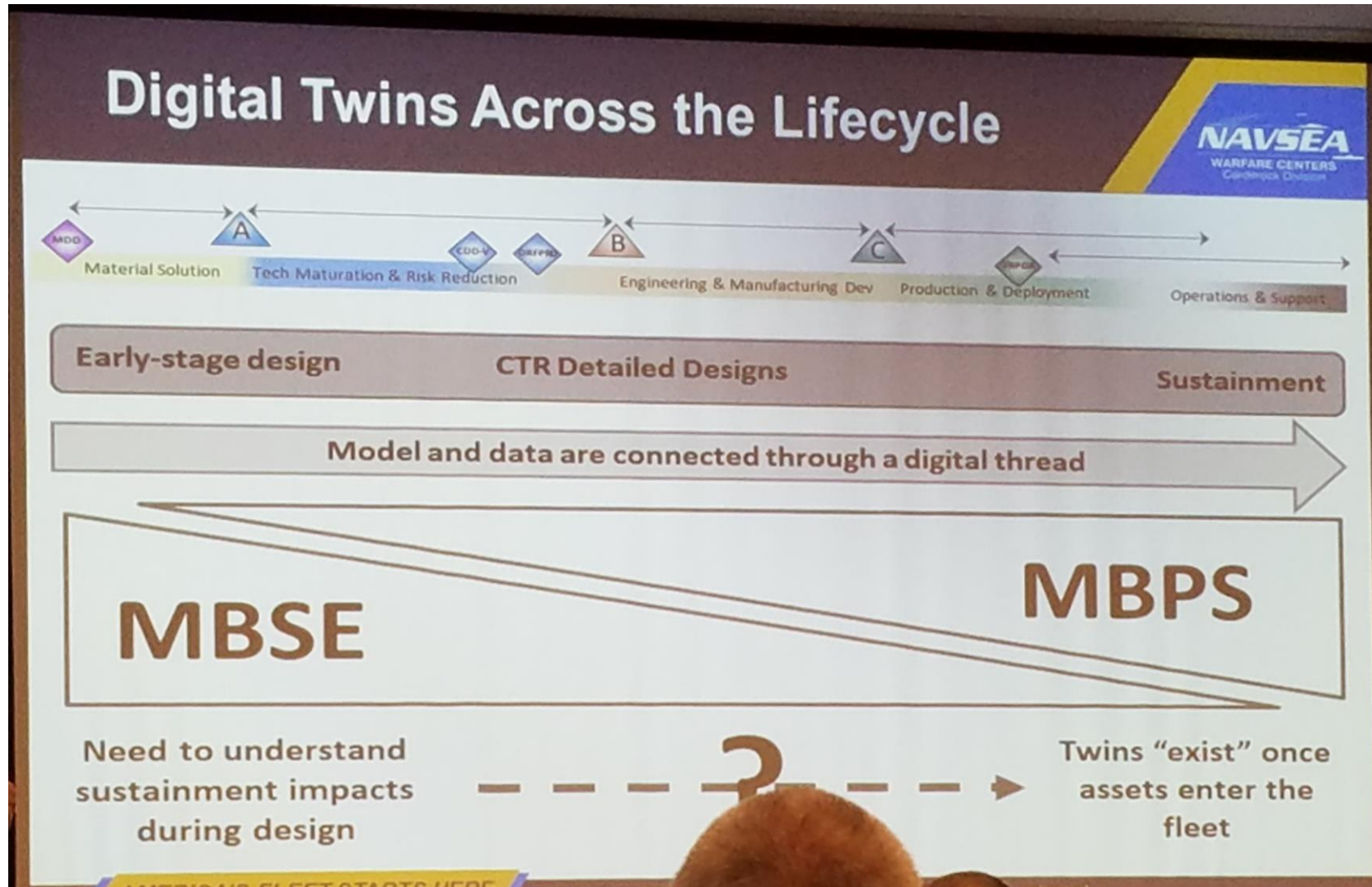
 What is the requirement ?

 What does it weigh?

 Does it work?

**Engineering Mockup**

# Digital Twins across the Defense Lifecycle





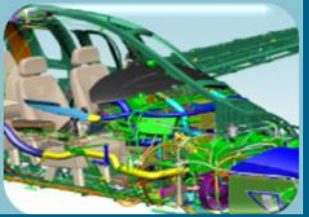






# Program Execution Excellence

## Digital Thread Solutions

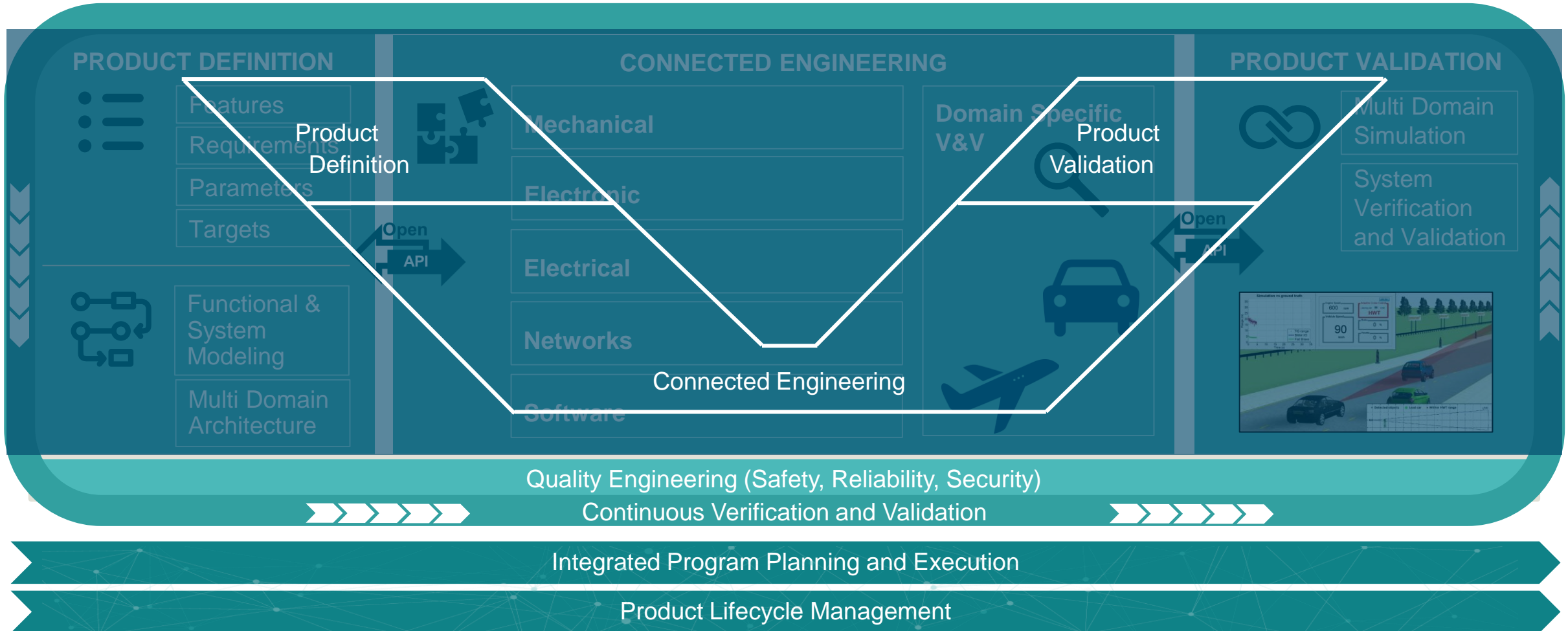
### Program Execution Excellence

#### Digital Thread Solutions on the Digital Innovation Platform

Model Based Systems Engineering	Integrated Prog. Planning and Execution	Product Engineering & Design	Supplier Source Selection and Management	Verification Management	Product Realization	Model Based Product Support
<b>OPTIMIZATION &amp; INNOVATION</b>	MEETING COST, SCHEDULE AND TECHNICAL REQUIREMENTS	EFFICIENT FIRST TIME RIGHT	EFFECTIVE SUPPLIER MANAGEMENT	FASTER TIME TO CERTIFICATION	MEETING COST & PRODUCTION GOALS	INTEGRATE SERVICE WITH THE FACTORY
<b>A Model Based Systems Engineering approach leveraging systems engineering and 3D models from idea thru to support.</b>	<b>A systems approach to project planning a fully planned, resourced, budgeted and executed program management solution.</b>	<b>Design with advanced materials, integrated CAD/CAE, maximize reuse, advanced configuration management.</b>	<b>Enabling traceability from OEM requirements to suppliers. Proactive supplier management.</b>	<b>Enabling traceability from requirements thru virtual and physical test to ensure product verification.</b>	<b>“Shift left” manufacturing planning to ensure cost, schedule &amp; safety goals are achieved with fully integrated factory.</b>	<b>Design for support. Plan for support. Manage service planning. Closed loop support with manufacturing and design.</b>
						

# Systems Digitalization

Start integrated, stay integrated



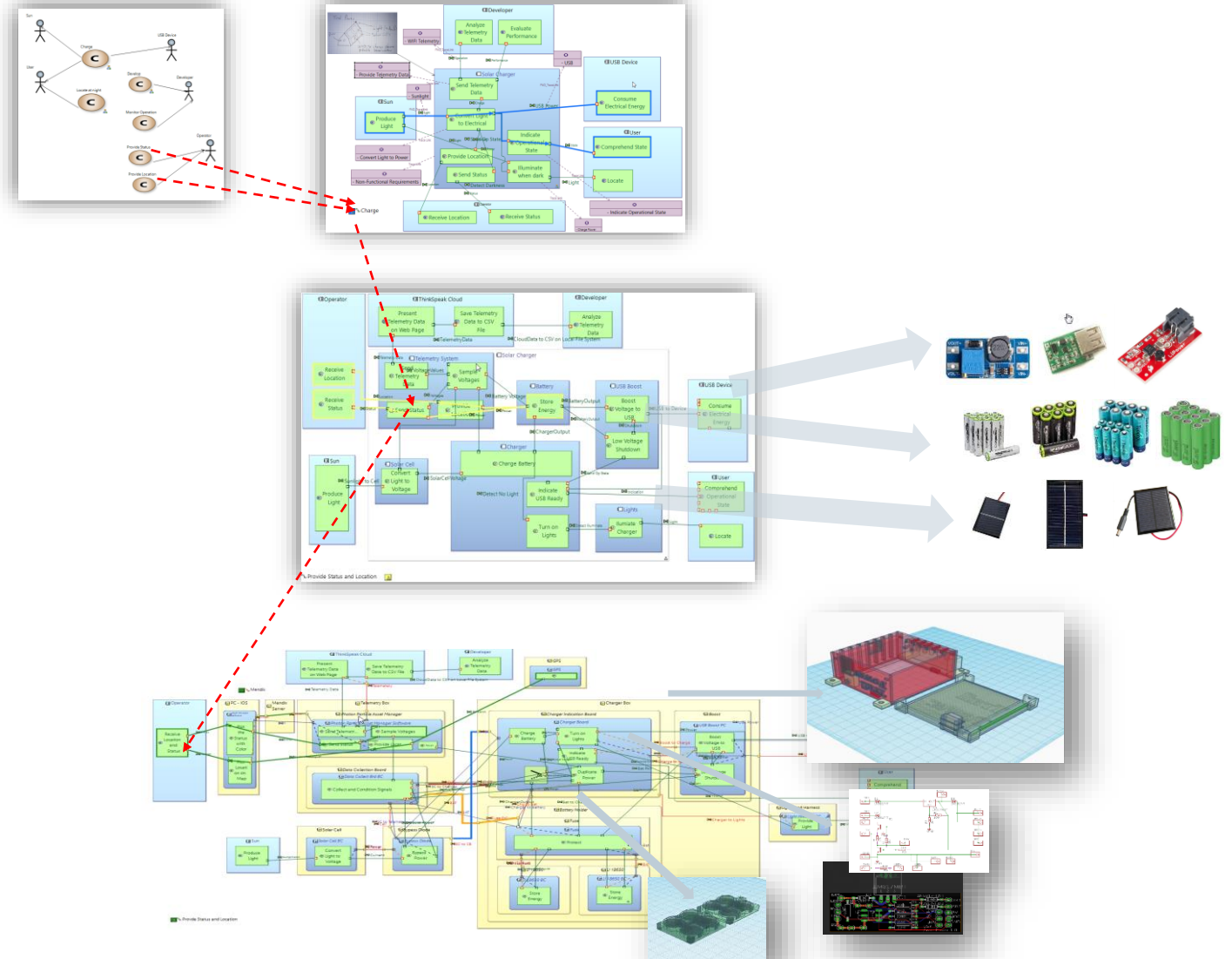
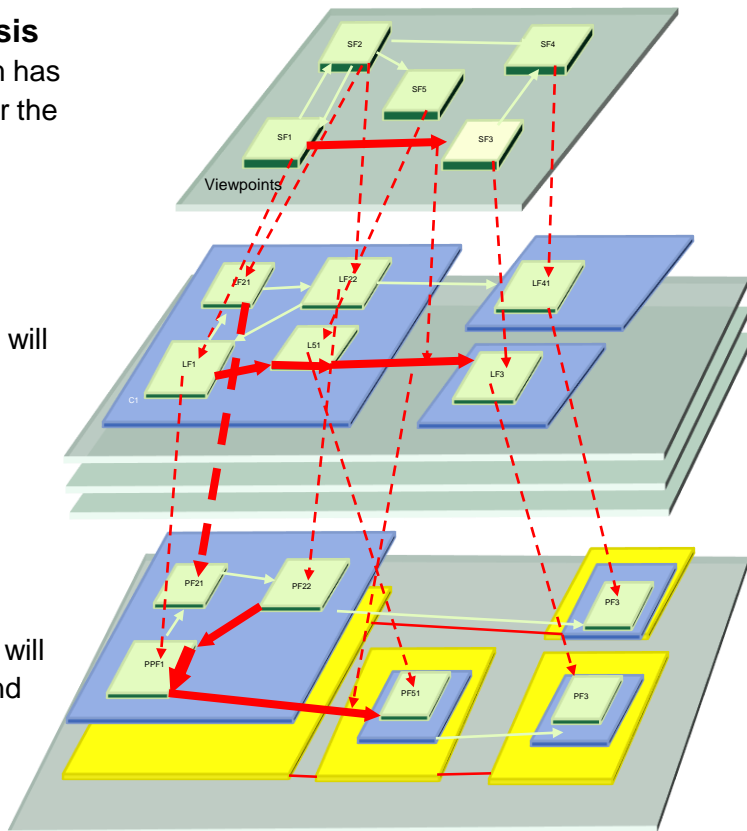
# What is Arcadia

## ARCADIA Phases supported by SMW

**System Analysis**  
What the system has to accomplish for the user.

**Logical Architecture**  
How the system will work to fulfil expectations..

**Physical Architecture**  
How the system will be developed and built.





# What is Capella

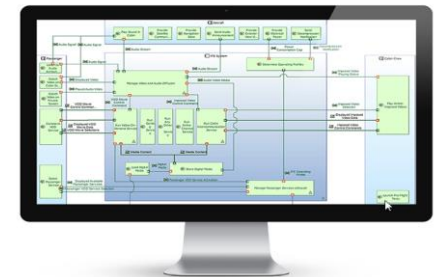


Capella is an Open Source solution for model-based systems engineering (MBSE). Hosted at [polarsys.org](https://polarsys.org), this solution provides a process and tooling for graphical modeling of systems, hardware or software architectures, in accordance with the principles and recommendations defined by the [Arcadia](#) method. Capella is an initiative of [PolarSys](#), one of several [Eclipse Foundation](#) working groups. [https://en.wikipedia.org/wiki/Capella\\_\(engineering\)](https://en.wikipedia.org/wiki/Capella_(engineering))

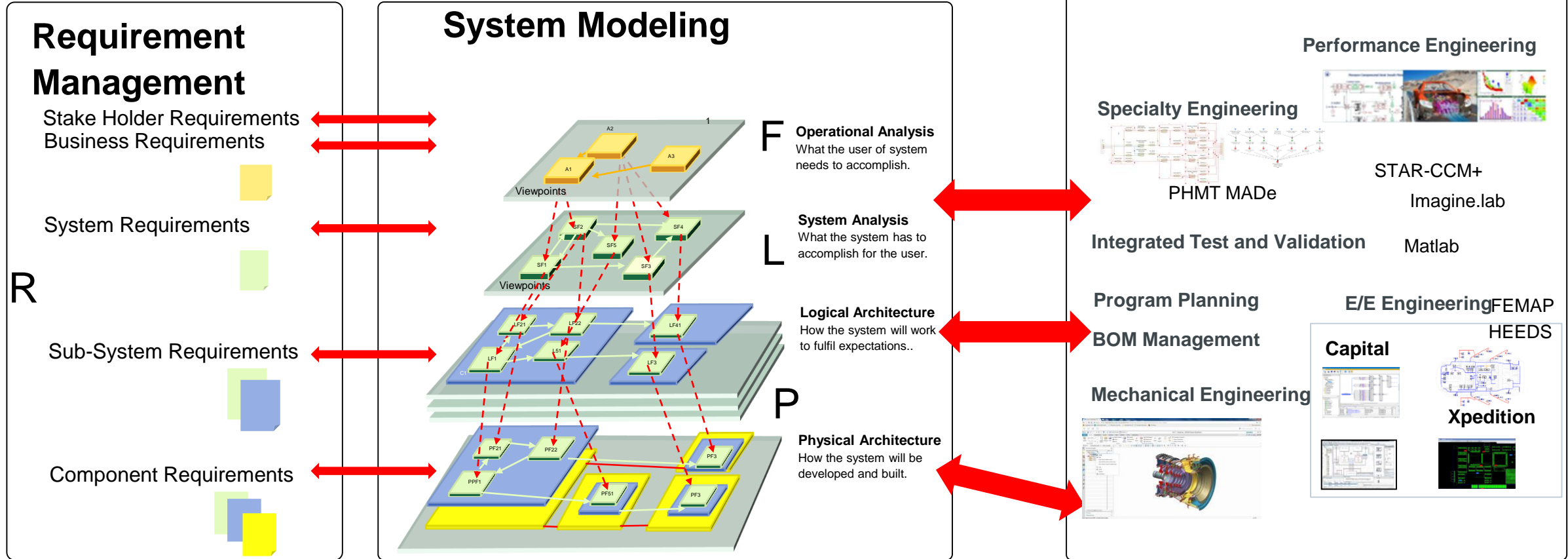
Open Source Solution for Model-Based Systems Engineering  
Comprehensive, extensible and field-proven MBSE tool and method to successfully design systems architecture <https://polarsys.org/capella/>

Formalize specification and master architectural design

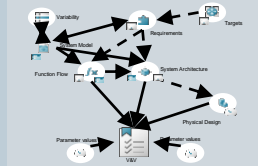
- Understand the customer need
- Define and share the solution
- Ensure engineering-wide collaboration
- Early evaluate and justify architectural choices
- Prepare and master V&V



# Creating end-to-end traceability



**TEAMCENTER**  
Common Information Model and PLM Services

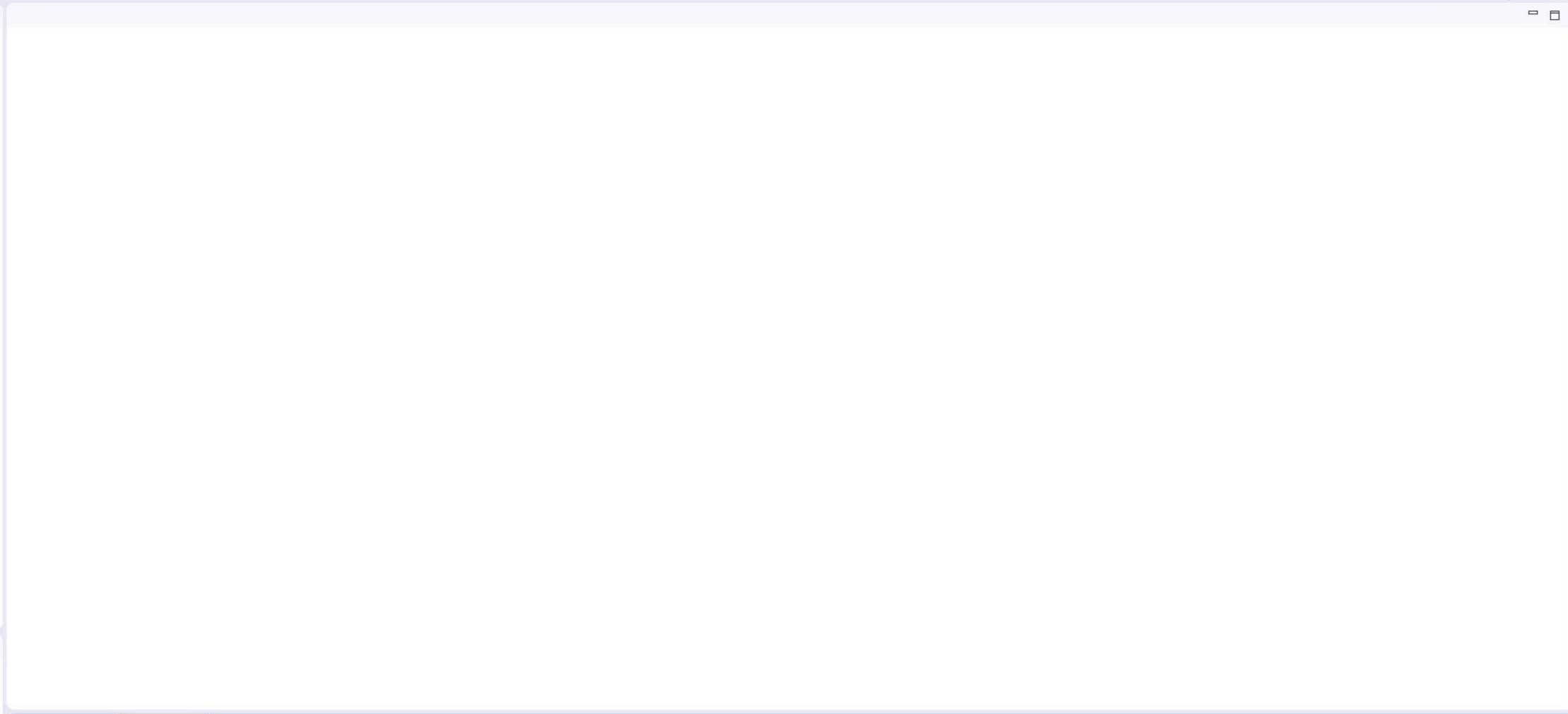




Capella Project Explorer

Select a name to find  
? = any character, \* = any string  
type filter text

Fast Linker



Semantic Browser Properties Information

Properties are not available.





# Multi-Domain Architecture



Open

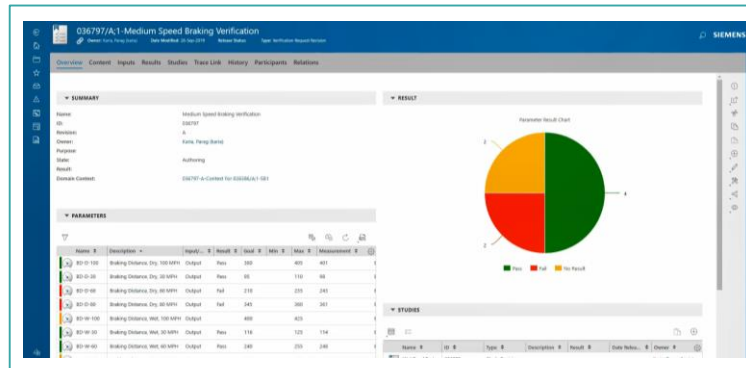
Integrated System Modeling

Verifiable

From Virtual Verification to Physical Testing

Future-Proof

Proven solutions ready for the future



Multi-Domain Architecture Produces the Blueprint for the Entire Product Lifecycle

File Edit View Layout Diagrams Options Tools Analyze Collaborate Teamcenter Window Help

Create Diagram Cruise Control

Containment Structure Diagrams

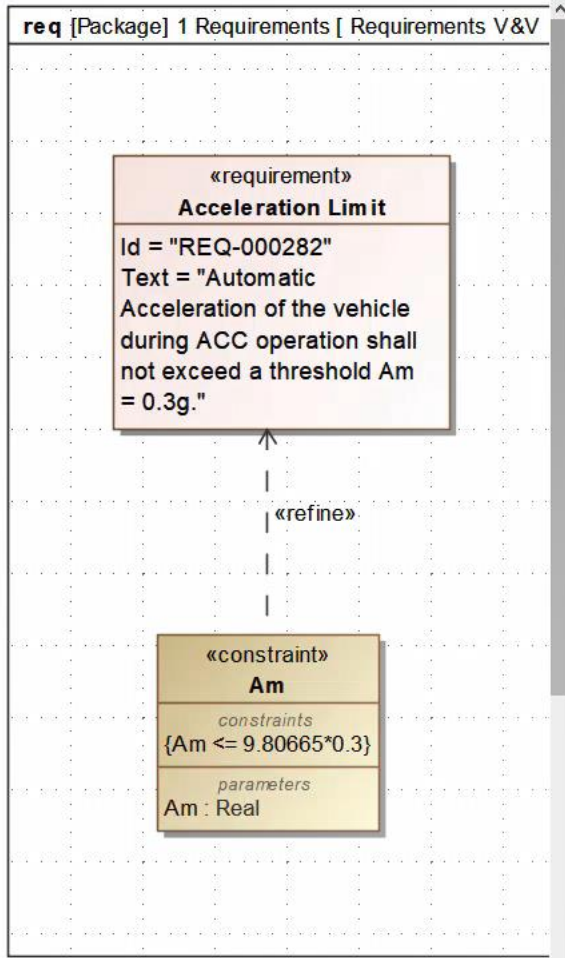
Containment

- Model (027212/A)
  - Logical Model
  - Physical Model
  - Simulation
  - StateAnalysis
  - zAuxiliary data
  - Adaptive Cruise Control\_Content

Selection

Tools

- Common
  - Note
  - Comment
  - Problem
  - Rationale
  - Element Group
  - Constraint
  - Containment
  - Abstraction
  - Dependency
  - Allocate
  - Image Shape
  - Diagram Overview
  - Legend
  - Text Box
  - Horizontal Se...
- Requirements Dia...
  - Requirement
  - Extended Re...
  - Constraint Block
    - Satisfy
    - Derive
    - Copy
    - Trace
    - Verify
    - Refine
    - Test Case Act...



Teamcenter Active Workspace

Teamcenter

INBOX

1 / 1 / 0  
New Total Past Due

FOLDERS

SAVED SEARCHES

ID DISPLAY RULES

PROJECTS

SCHEDULE TASKS

SCHEDULES

SUBSCRIPTION

DPV

PEOPLE

PREFERENCES

ACTIVE MODELER

LOGICAL OBJECTS

QUALITY MASTER DATA

# Multi-Domain Simulation



Open

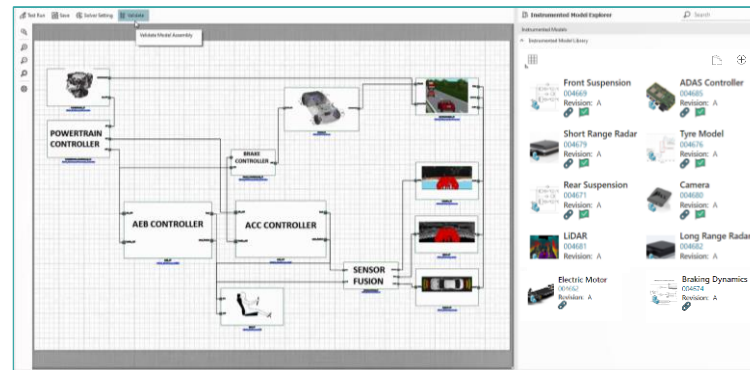
Integrated Behavior Modeling  
and Simulation

Configurable

Scalable and Reusable  
Simulations

Standard

Facilitate Collaboration  
Maximize Reuse

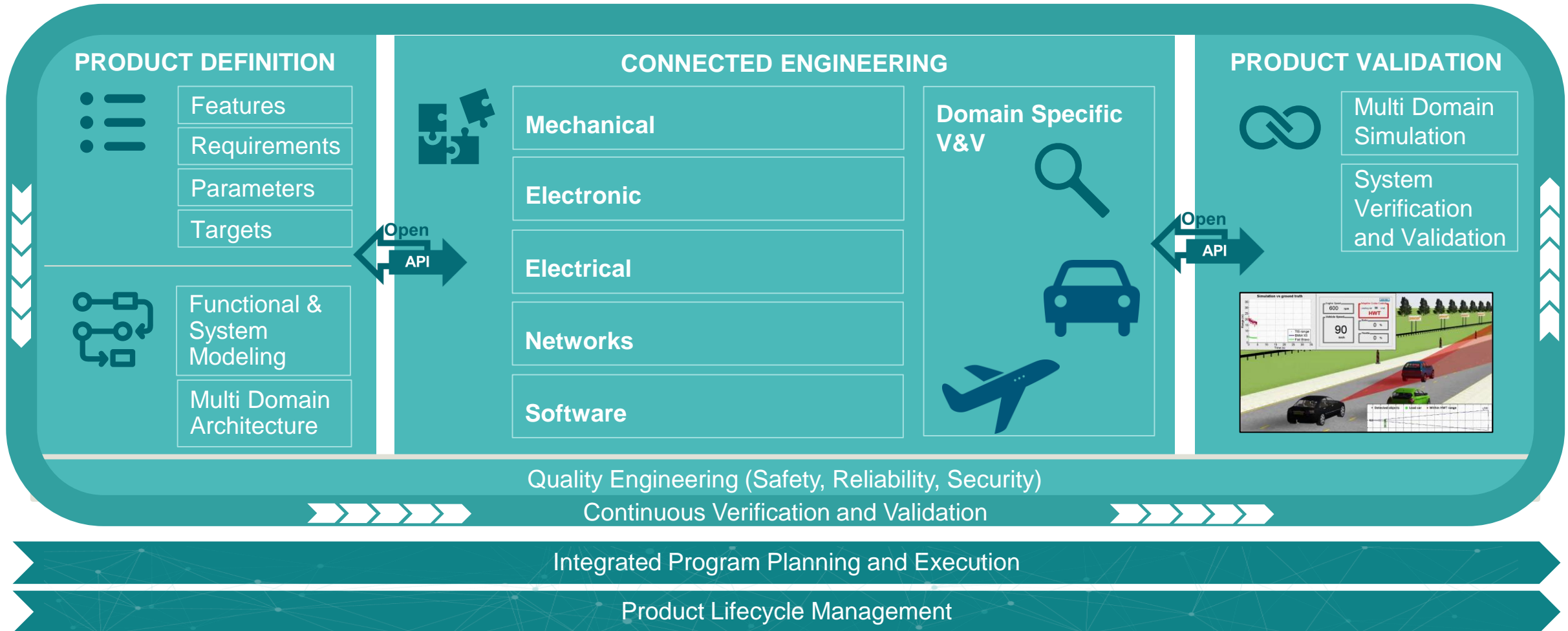


Multi-Domain Simulation to enable Closed-Loop Performance Engineering

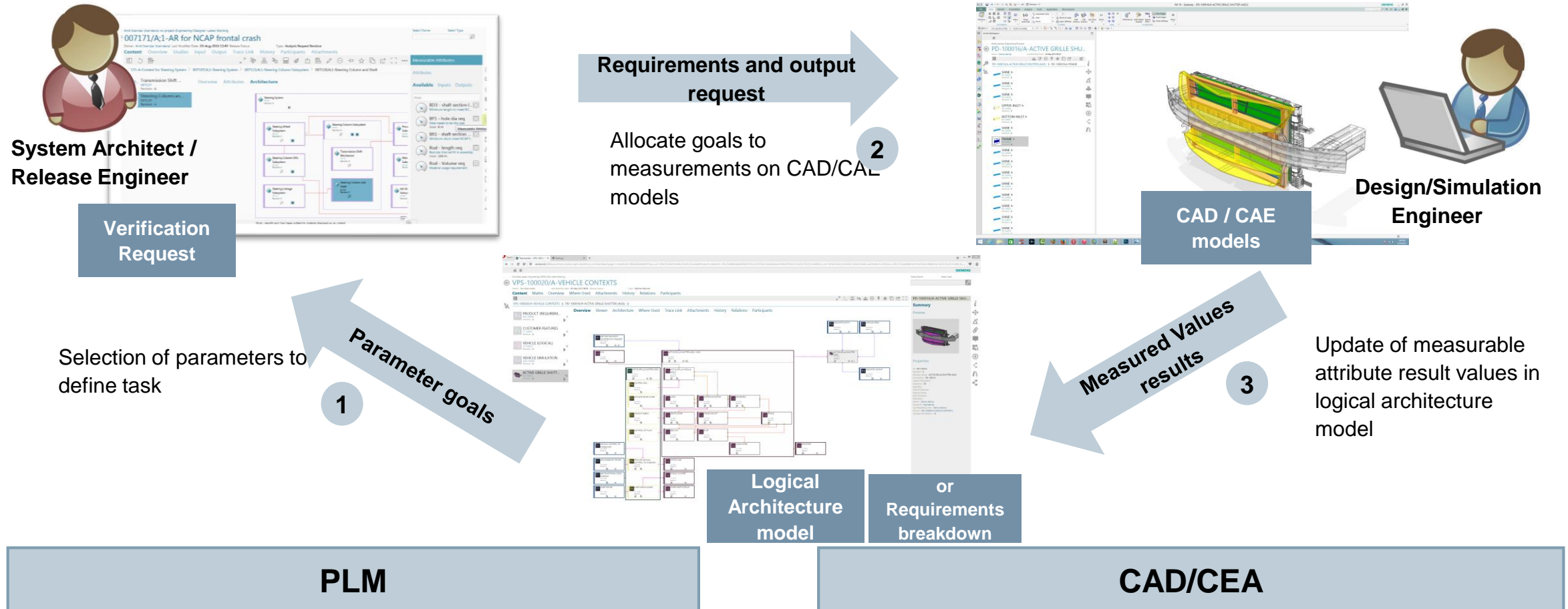


# Systems Digitalization

Start integrated, stay integrated

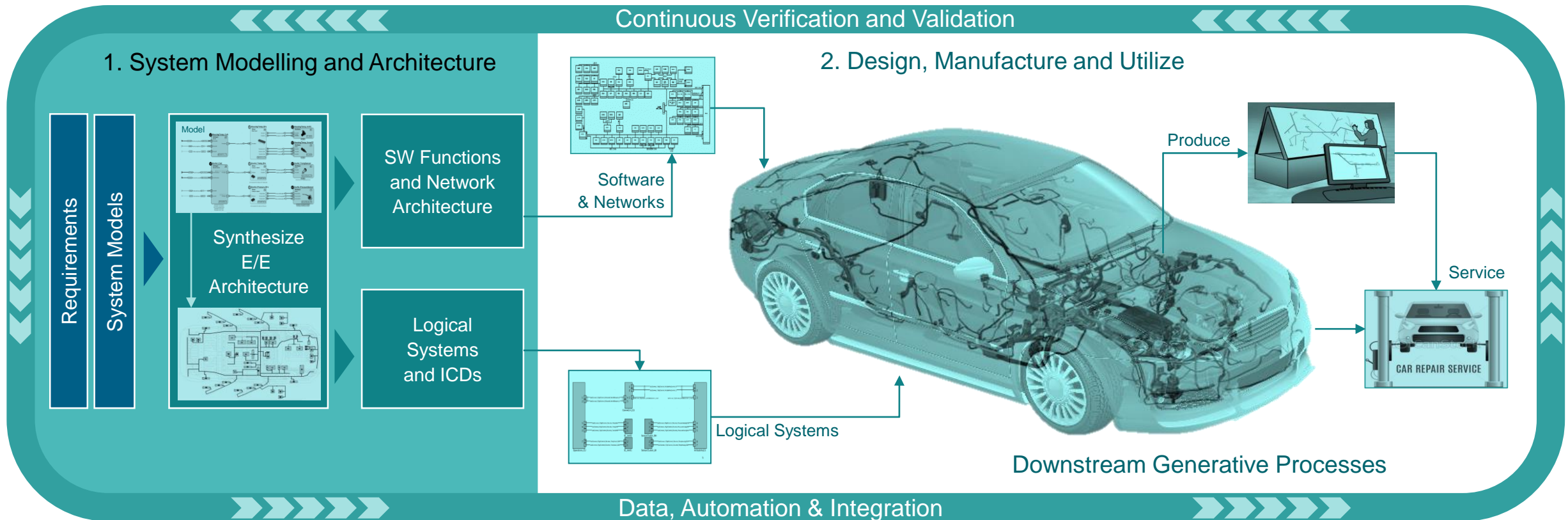


## Typical user workflow



# Two Key Stages in E/E Systems Development

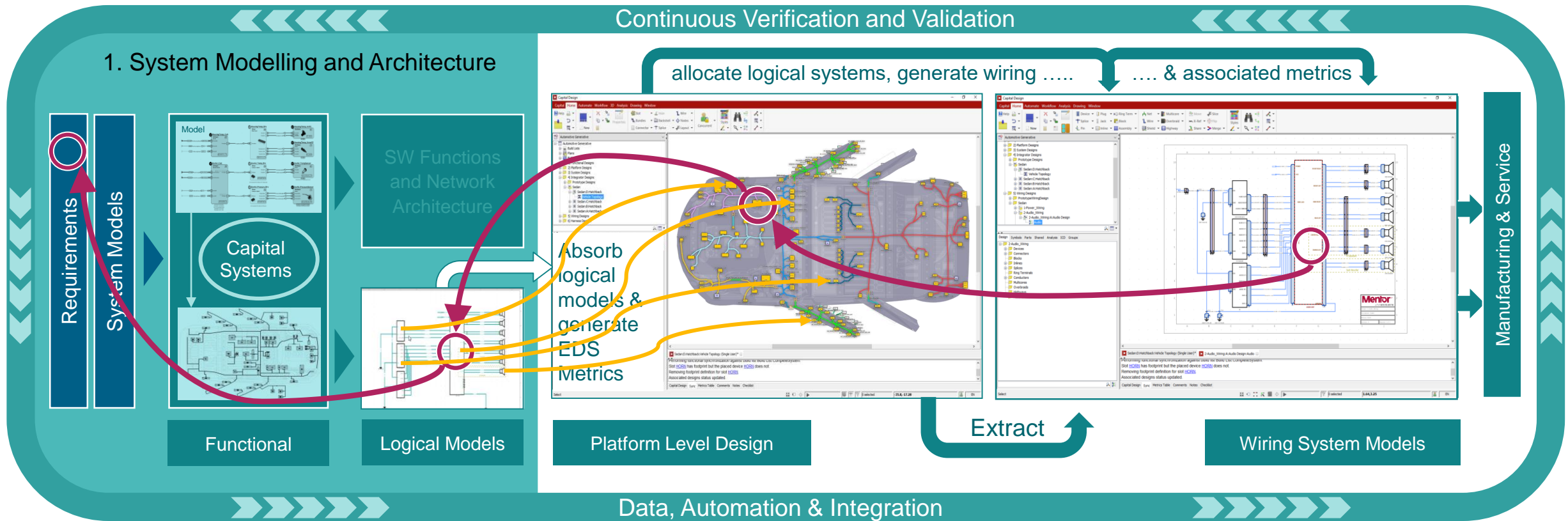
## Architecture Optimization & Creation of Downstream Added Value





# Downstream – Electrical Distribution System Design

## Generative Design and Validation of Wiring with Full Traceability



# Optimize Software In Complex Products

## Continuous integration of hardware & software lifecycles



### Hardware-Software Integration Challenges

#### HW & SW Lifecycle Synchronization

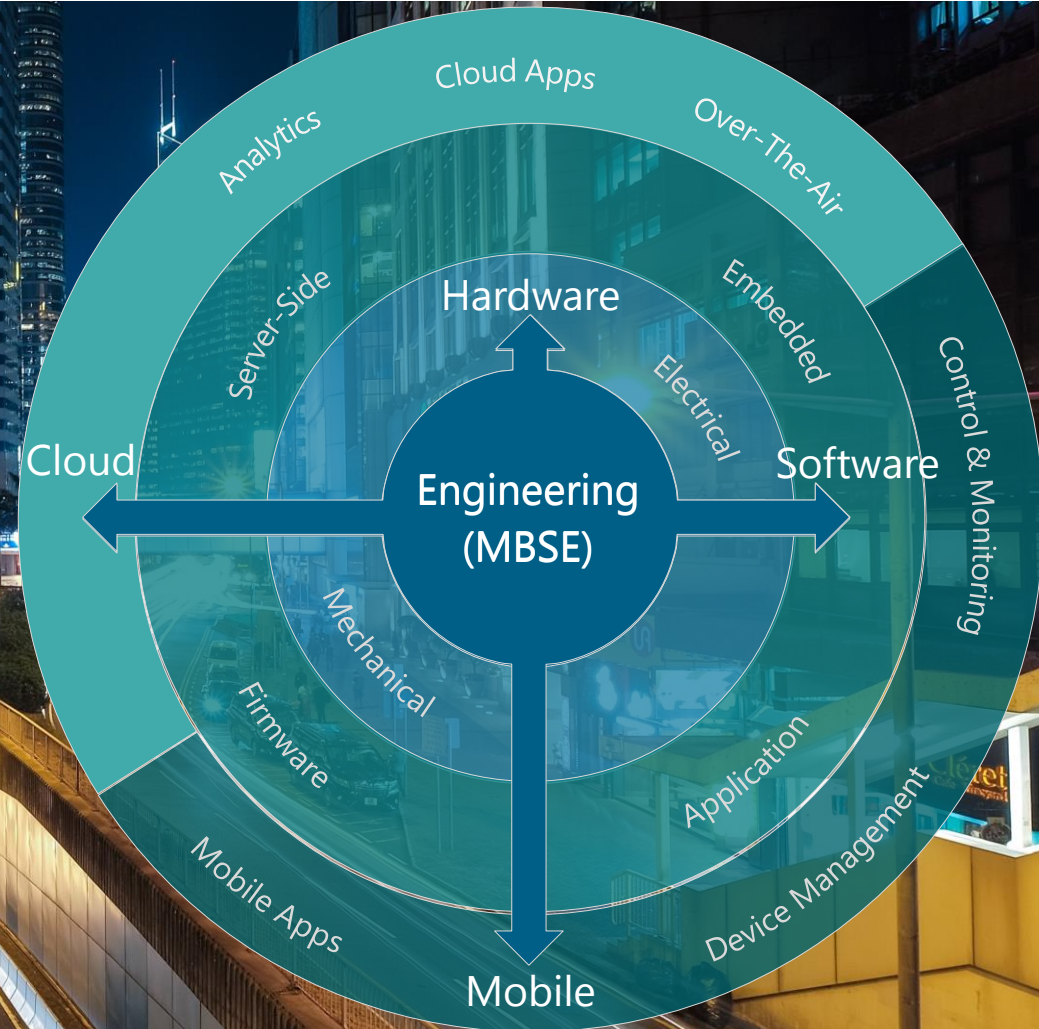
Best in class tools, integrated

#### Continuous Integration & Development

Traceability from requirements to development to simulation (HiL, SiL, MiL) to test

#### Greater Complexity & Variability

Integrated BOM and configuration



# Orchestrate Development Across the Application Lifecycle



## Software lifecycle in Polarion

## Teamcenter multi-domain Bill-of-Materials

**DP-550 - System Application SW Version 2.0**  
System Application Software

Type: **Release**

Release Plan: **Version 2.0** (2019-6-05)

Release QA: (2019-3-05)

Release PM: (2019-4-05)

Feature Freeze Date: (2019-5-05)

Code Freeze Date: (2019-6-03)

Public Launch: (2019-7-05)

**Executable, Calibration, Installer, etc.**

Element Name	ID	Revision Name	Description
Refrigerator	026164	Refrigerator	Refrigerator
Door Assembly	026165	Door Assembly	
Cabinet Assembly	026166	Cabinet Assembly	
Console	026179	Console	
Harness	026185	Harness	
Motor Control Assembly	026186	Motor Control Assembly	
Motor Configuration Data	026189	Motor Configuration Data	Motor Configuration Data
Motor Calibration Data	026191	Motor Calibration Data	Motor Calibration Data
Motor Housing	026192	Motor Housing	Motor Housing
Motor	026193	Motor	Motor
Motor Control PCA	026194	Motor Control PCA	Motor Control PCA
Motor Control SW	026201	Motor Control SW	Motor Control SW
Power Cord	026187	Power Cord	Power Cord

**Electronics**

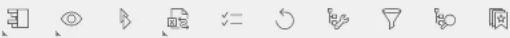
**Wire Harness**

## Integrated hardware and software management



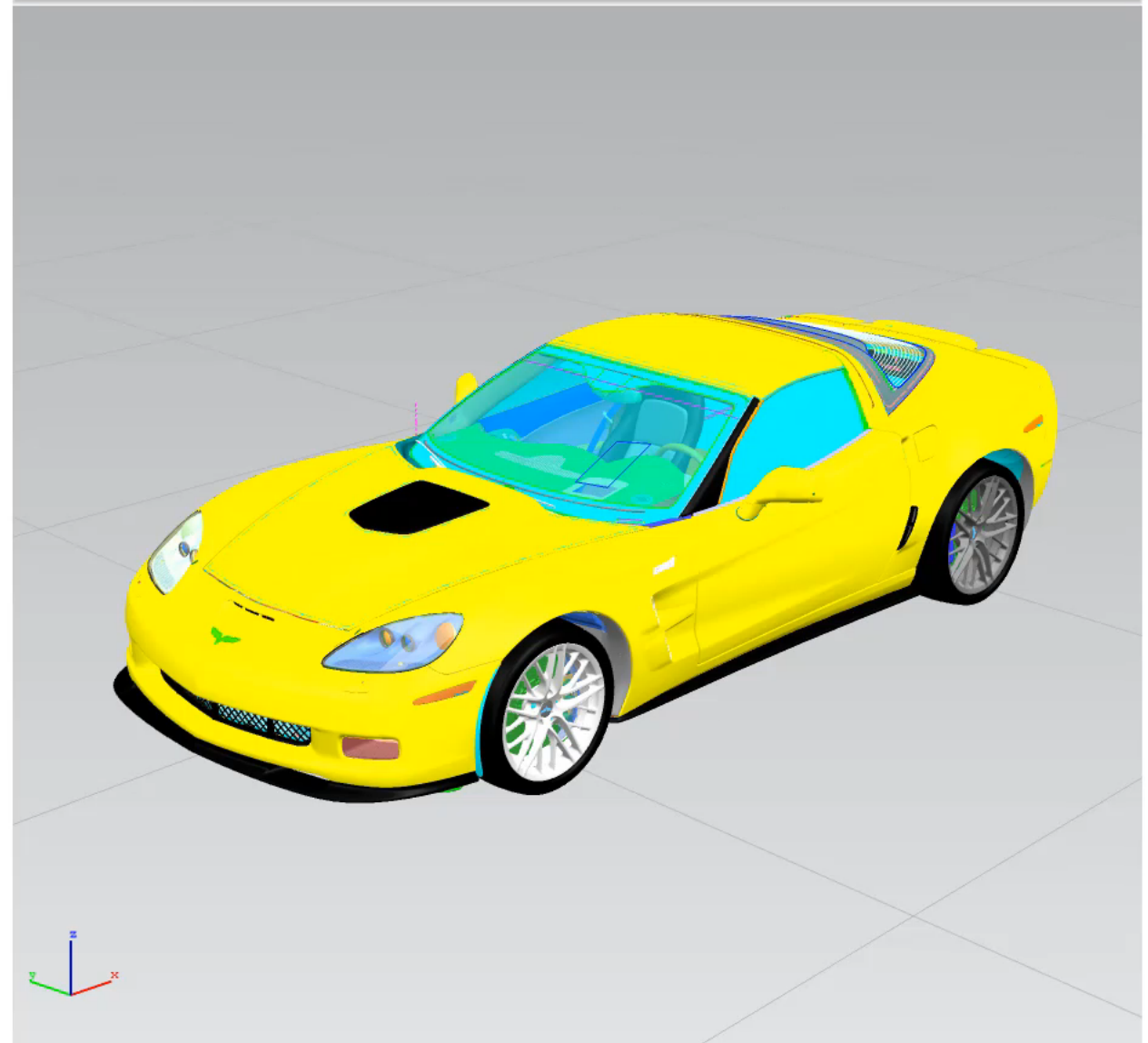
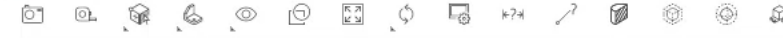


## Content Changes



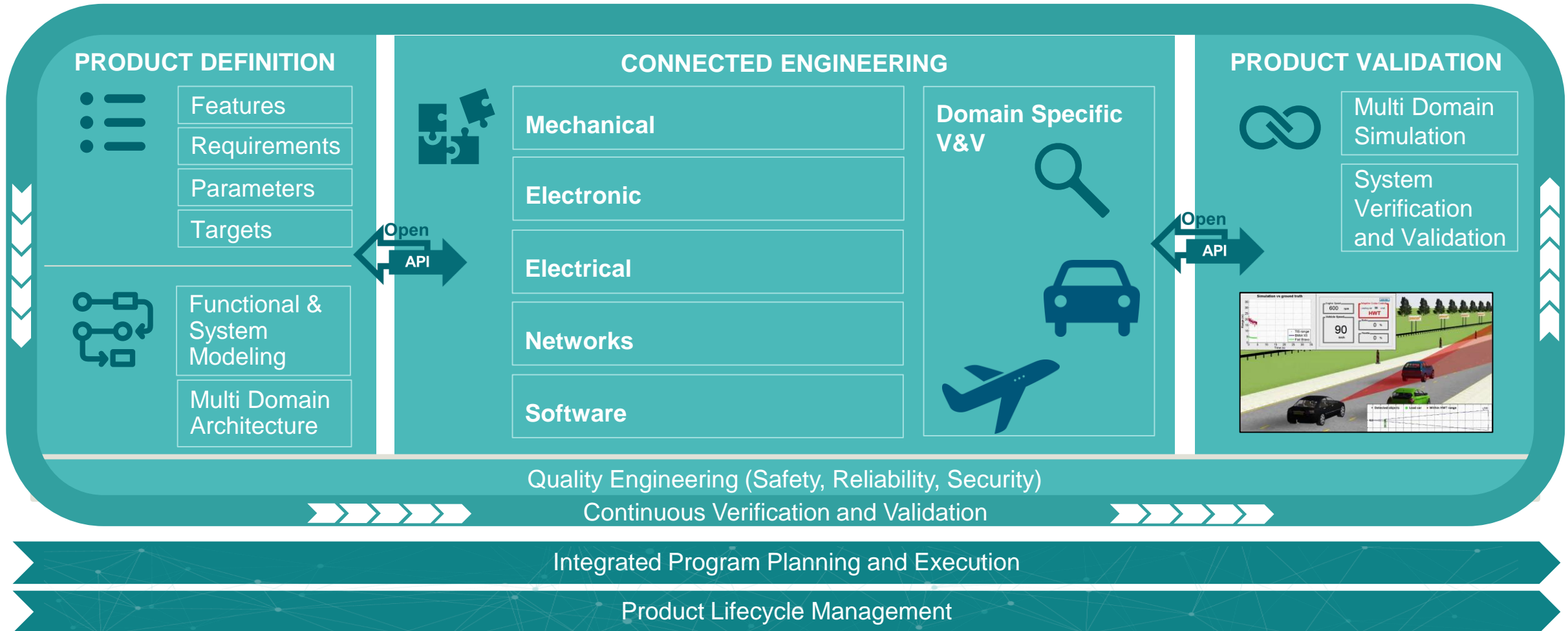
Element Name	Type	Variant Formula
ENGINE 6.2L V8 DI	Design	Engine = '6.2L V8 DI"L V8 DI'
ENGINE 6.2L Supercharged V8 DI and PDFI	Design	Engine = '6.2L Supercharge V8 DI'
IA-HARN ASM WRG-ENGINE LS9-Y-MM	Design	
6.2L DL MAN MASTER ENGINE WRG HARN	Harness	Transmission = '7-speed manual' AND Engine = '6.2L V8'
6.2L DL AUTO MASTER ENGINE WRG HARN	Harness	Transmission = '8-speed paddle shift automatic' AND Er
6.2L SC AUTO MASTER SC ENGINE WRG HARN	Harness	Transmission = '8-speed paddle shift automatic' AND Er
6.2L SC MAN MASTER SC ENGINE WRG HARN	Harness	
MASTER ENGINE CONTROL MODULE ASM	Design	
MODULE ASM-ENG CTRL	Harness Module	
ENG CTRL PCB	EDA Printed Cir...	
Eng Cntrl 6,2L SC MAN SW	Software	Transmission = '7-speed manual' AND Engine = '6.2L Su
Eng Cntrl 6.2L MAN SW	Software	Transmission = '7-speed manual' AND Engine = '6.2L V8'
Eng Cntrl 6,2L SC AUTO SW	Software	Transmission = '8-speed paddle shift automatic' AND Er
Eng Cntrl 6.2L AUTO SW	Software	Transmission = '8-speed paddle shift automatic' AND Er
MODULE ASM - ELEK SUSP CONT	Harness Module	
Fasteners	Design	
ECM BRKT	Design	
BRACKET-WRG HARN	Design	
IA-MODULE AND BRACKET-Y-MM	Design	
IA-FRONT R/H SIDE DR -Y-MM	Design	
IA-TIRES,WHEELS&TRIM-Y-MM	Design	
IA-ECE FRONT LIGHTING-Y-MM	Design	
IA-FRT INT AIRFLOW COMMON Y-MM	Design	
IA-INFOTAINMENT-Y-MM	Design	
IA-GMX321 I/P ASM-Y-MM	Design	
IA-HARN ASM WRG-DOOR TRIM -Y-MM	Design	

## 3D Variants Overview Finishes Made From Where Used Changes Attachments History Relations Collaboration



# Systems Digitalization

Start integrated, stay integrated



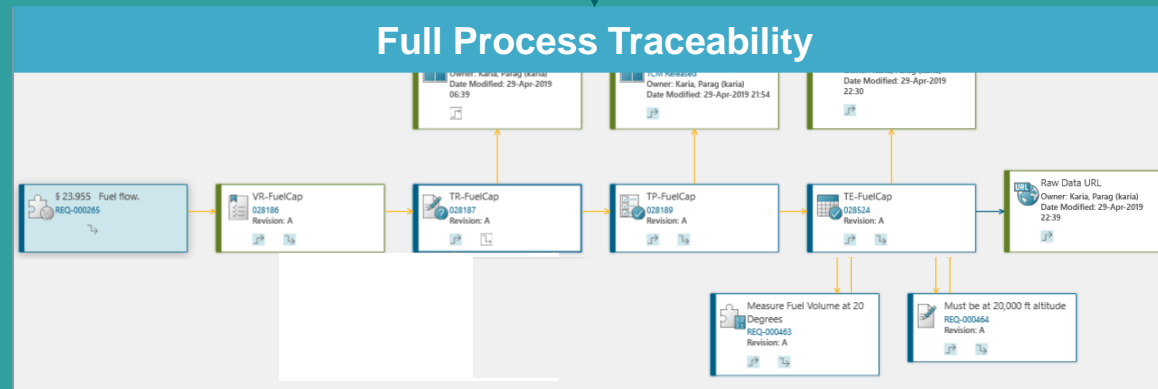
# Verification Management

## Pulling it all together

**SIEMENS**  
Ingenuity for life



Multi-domain  
Virtual or physical  
Support for all models  
Fully traceable





# Small Car

Advanced Search

Owner: joez (joez)

Date Modified: 16-Jan-2017 12:10 Release Status:

Type: Program

[Overview](#) [Plan](#) [Events](#) [Changes](#) [Deliverables](#) [Schedules](#) [Attachments](#)

## Plan Levels

NAME	TYPE	STATE
Small Car	Program	Not Started
Model Year 2019	Project	Not Started



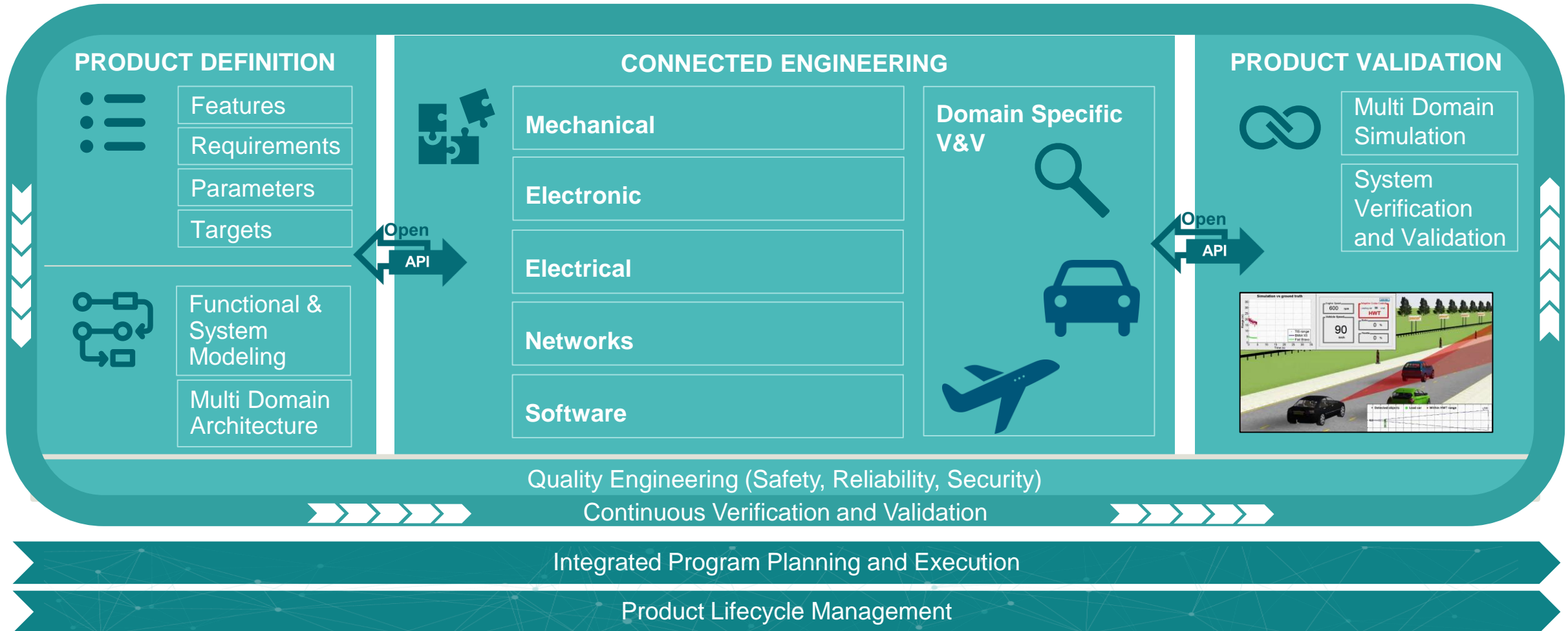
## Plan Level Events

No Events found



# Systems Digitalization

Start integrated, stay integrated



## **Vision**

MBSE: start integrated stay integrated throughout the complete lifecycle

## **Technology strategy**

Open Eco system to incorporate MBSE tooling standards in the market place

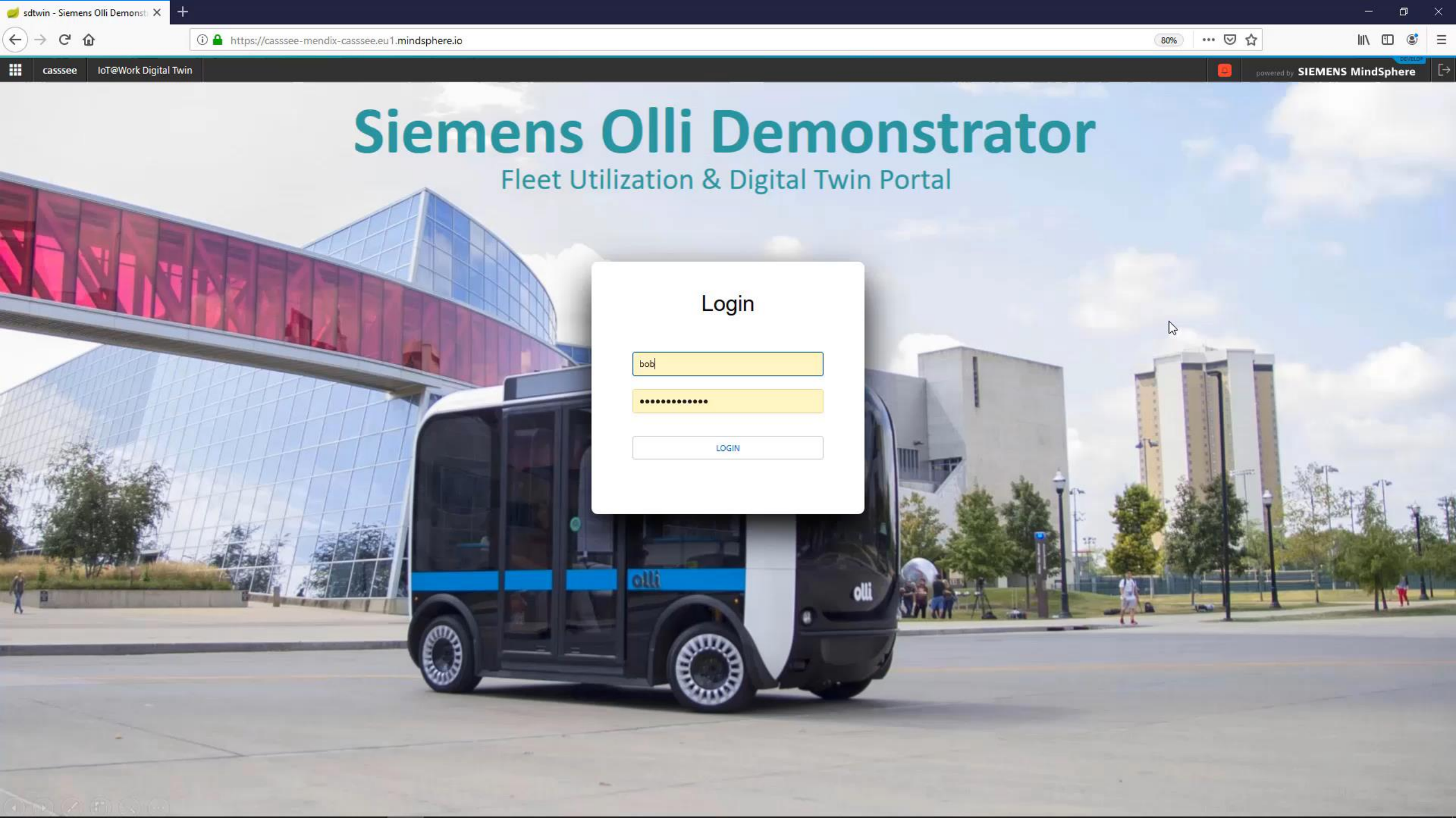
## **Solutions offering**

Siemens provides System Modelling Workbench which integrates MBSE with TC (PLM)

## **Goal**

Enabling continuous V&V: to speed up development, reduce/prevent errors





# Siemens Olli Demonstrator

## Fleet Utilization & Digital Twin Portal

**Login**

# Agenda



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# Trends & Challenges

**Increase in  
product  
variants**

**Regulatory  
Compliance**

**Global  
Setup**

**Fast  
changing  
consumer  
demands**



**High  
Quality  
Demand**

**Global  
Supply  
Chain**  
Operational  
Cost and  
Quality

**Stressed financial and  
program performance**

**World Wide  
Competition**

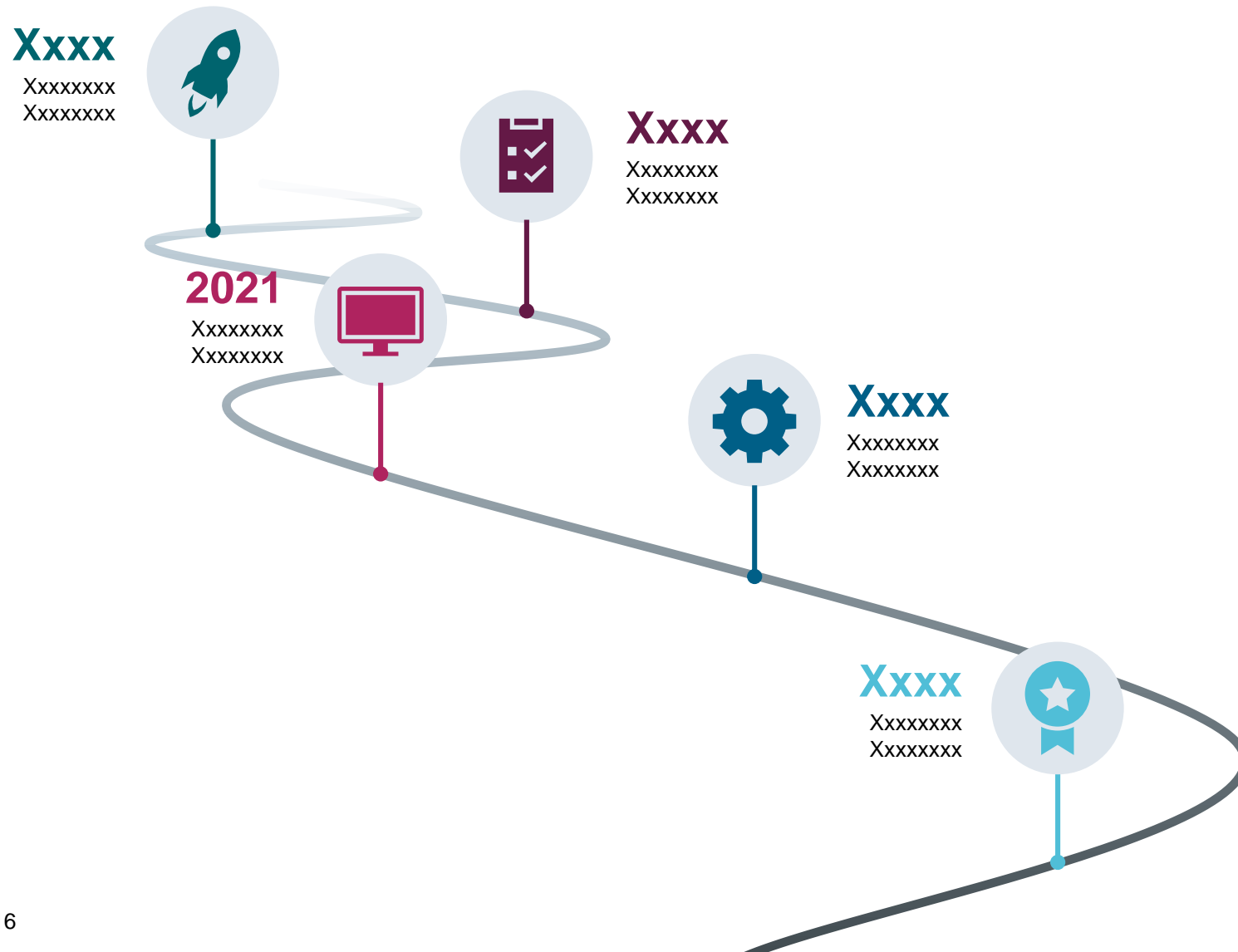


# Well known (often used) Requirement Management solutions

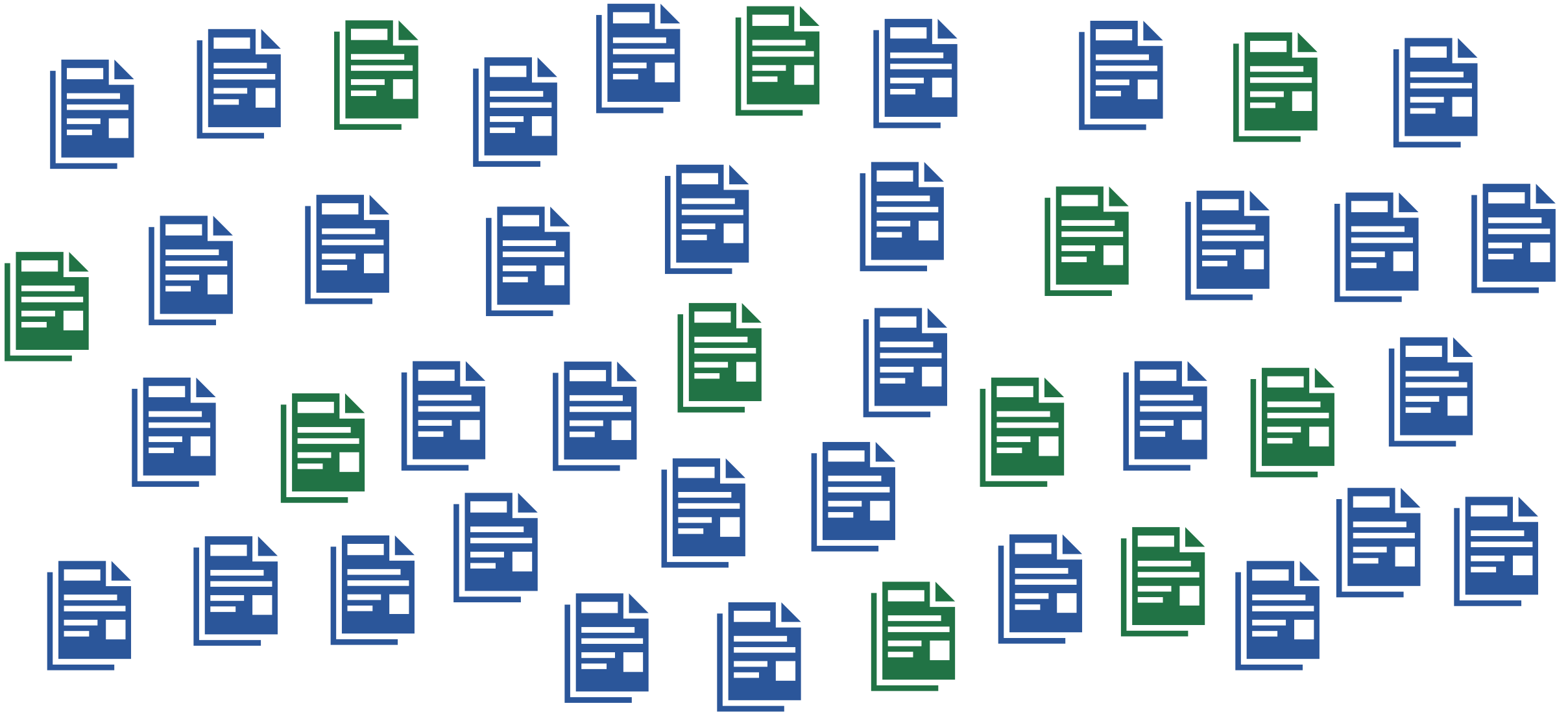
**SIEMENS**  
*Ingenuity for life*



# Roadmap

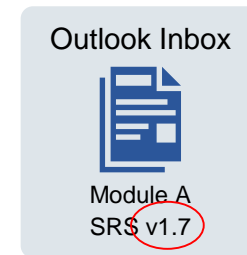
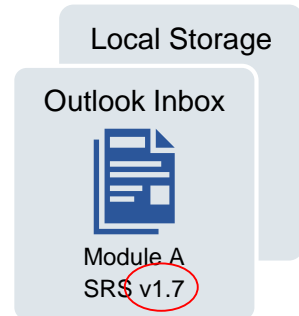
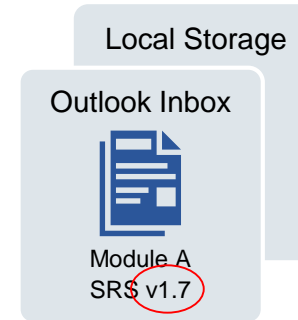
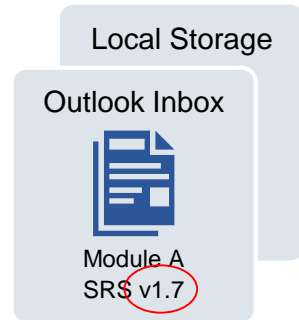
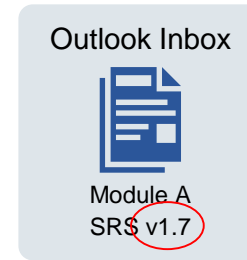
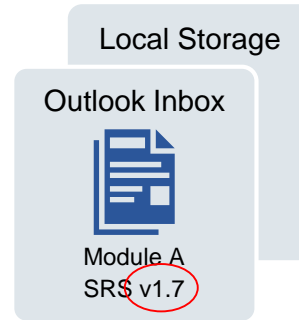
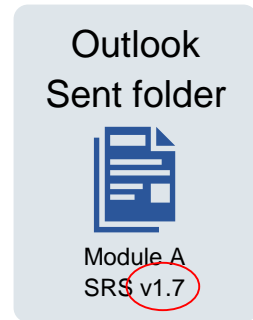
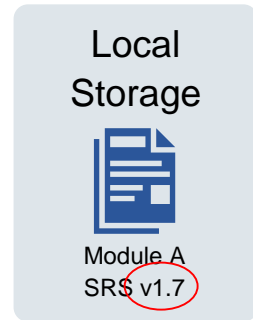
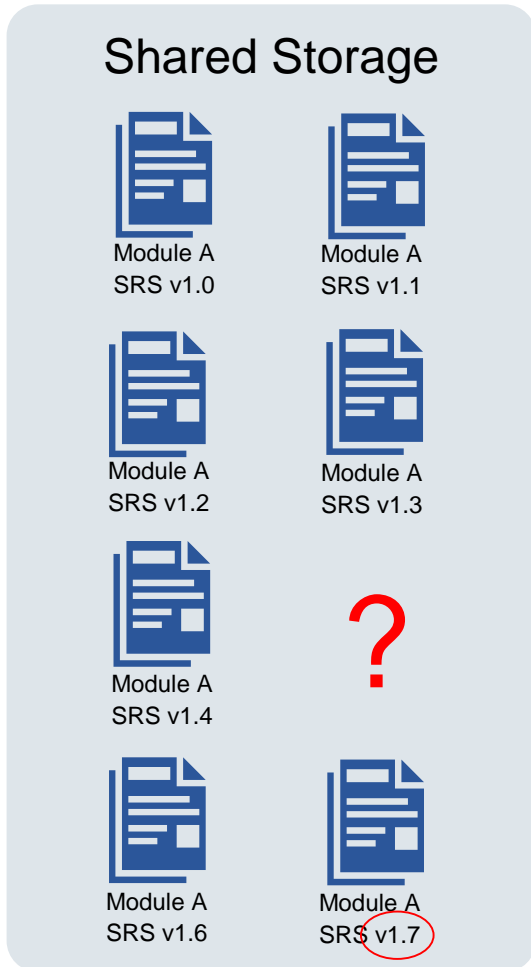


# Massive number of specification documents

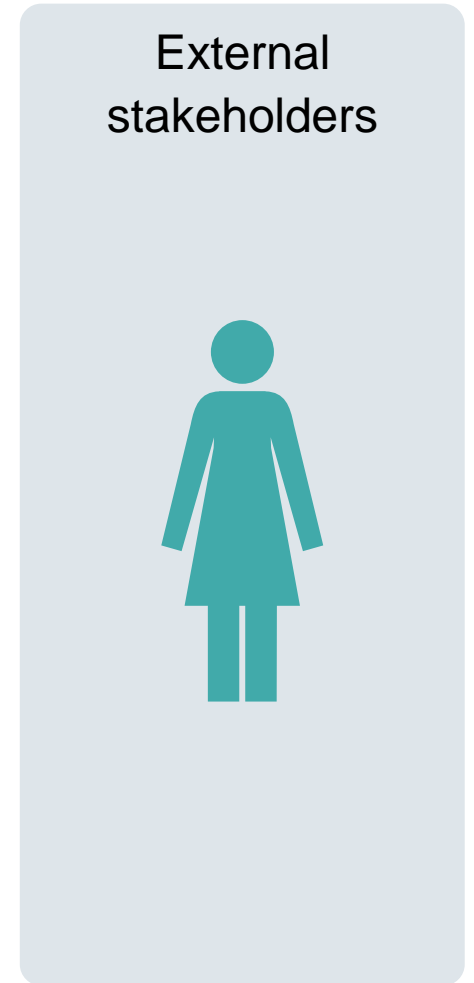
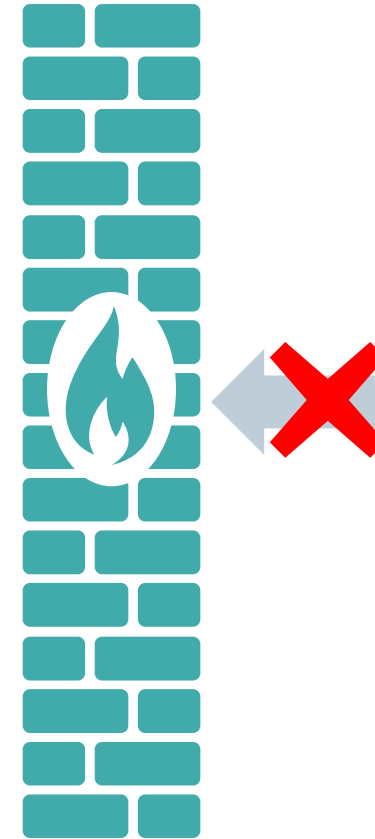
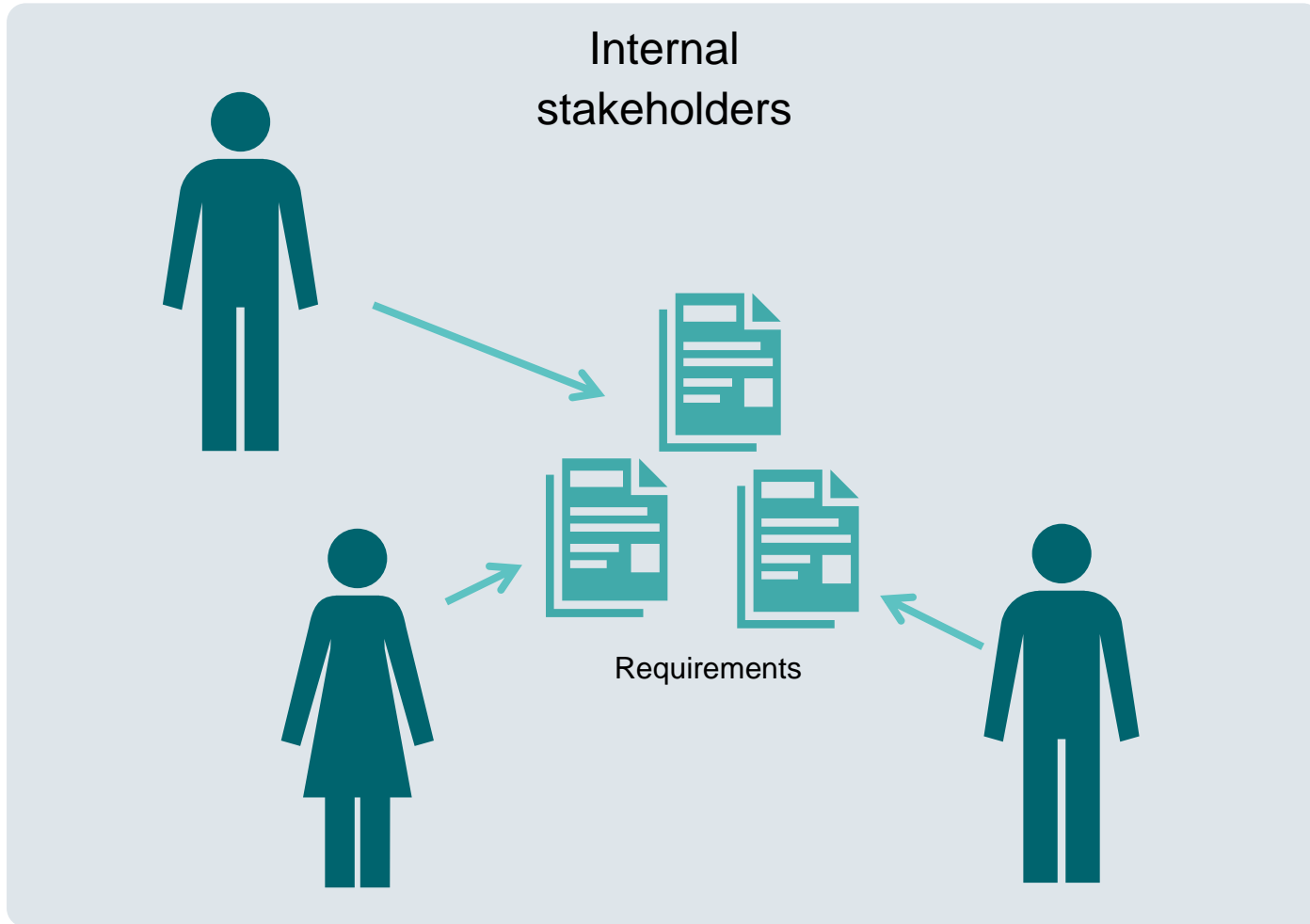




# Single source of truth



# External stakeholders

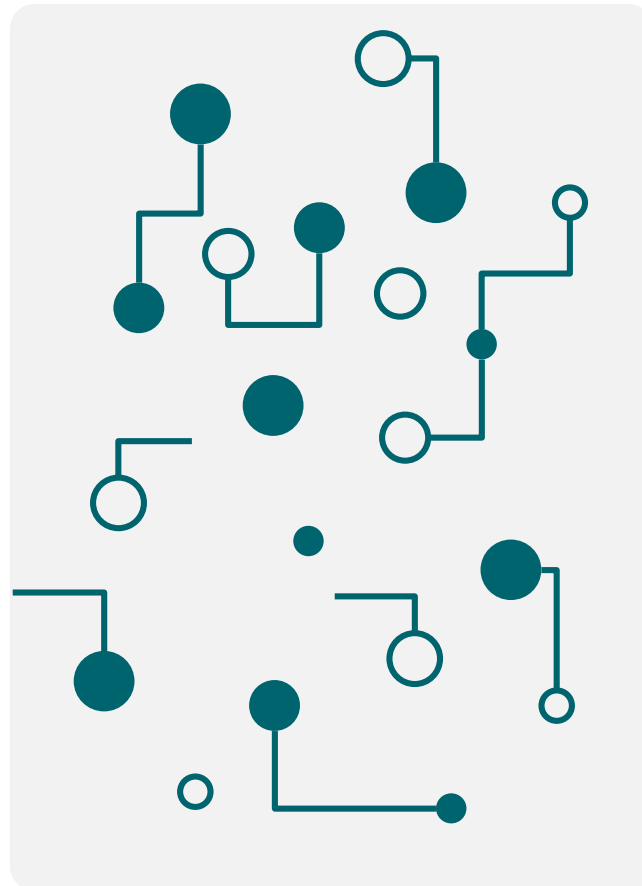


# Challenges

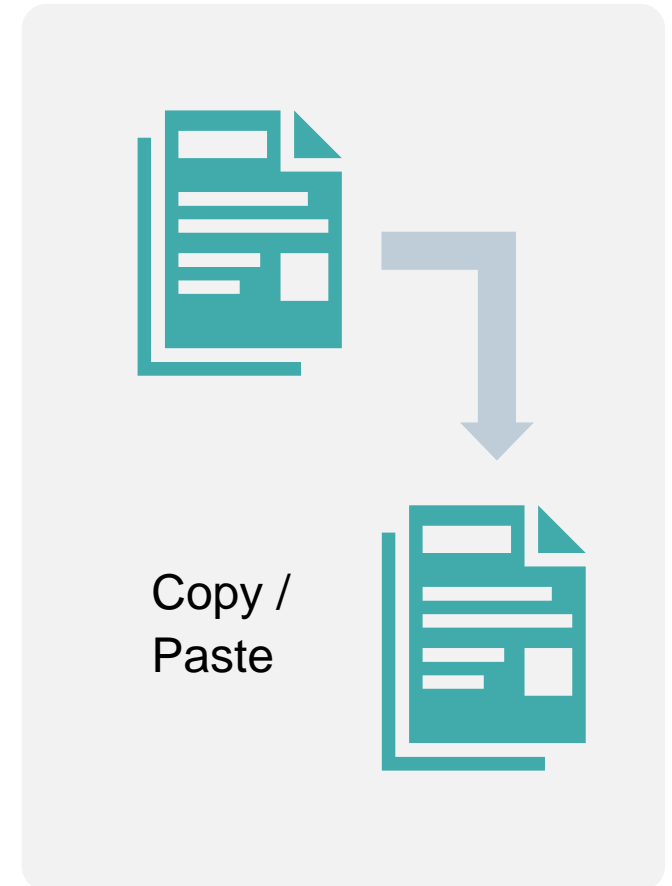
## Collaboration



## Traceability



## Re-use





Stay close to  
what you are  
familiar with

&

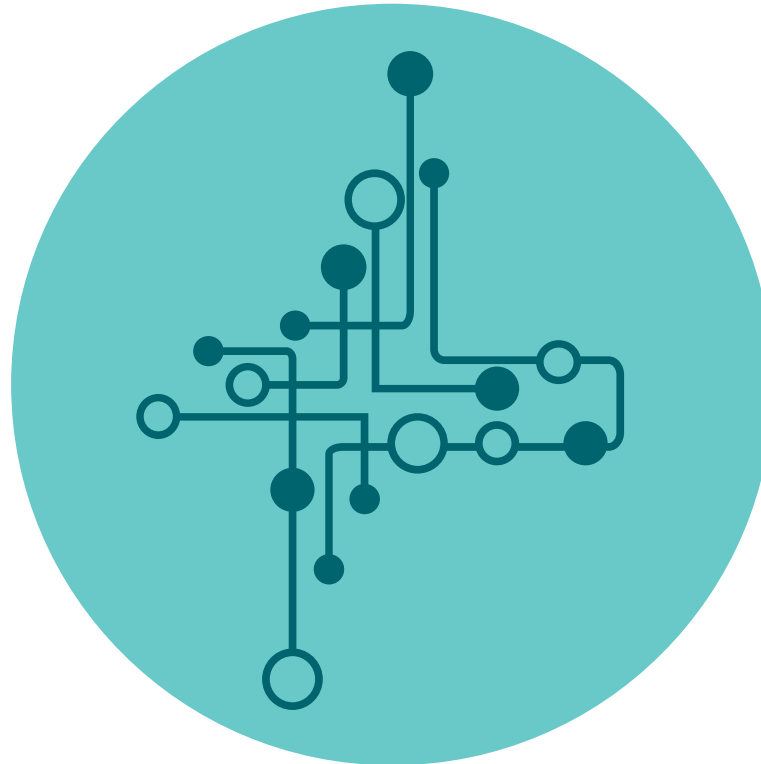
Improve the way  
you manage  
requirements

# Lifecycle Management core pillars

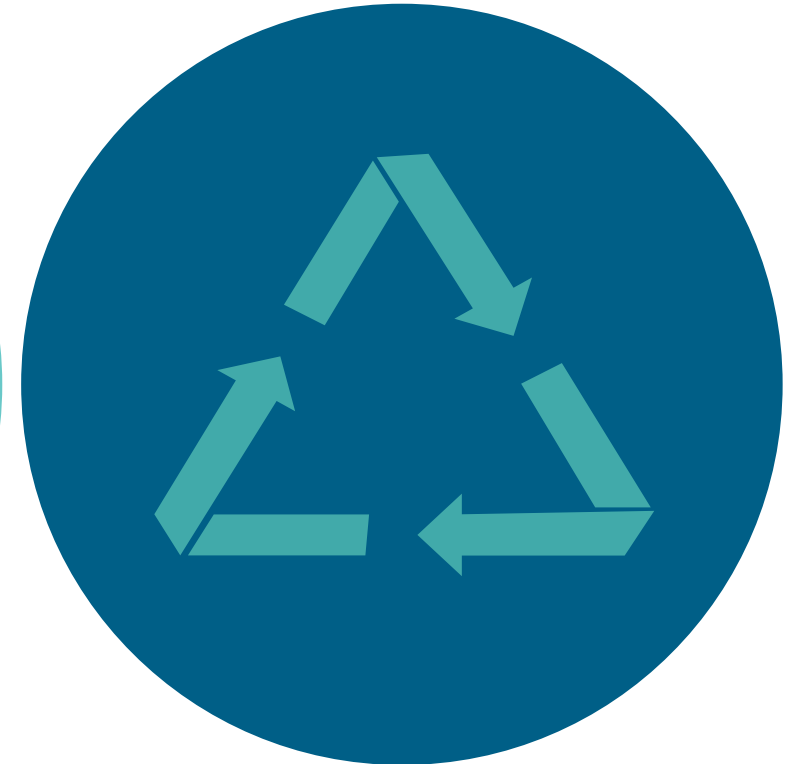
## Collaboration



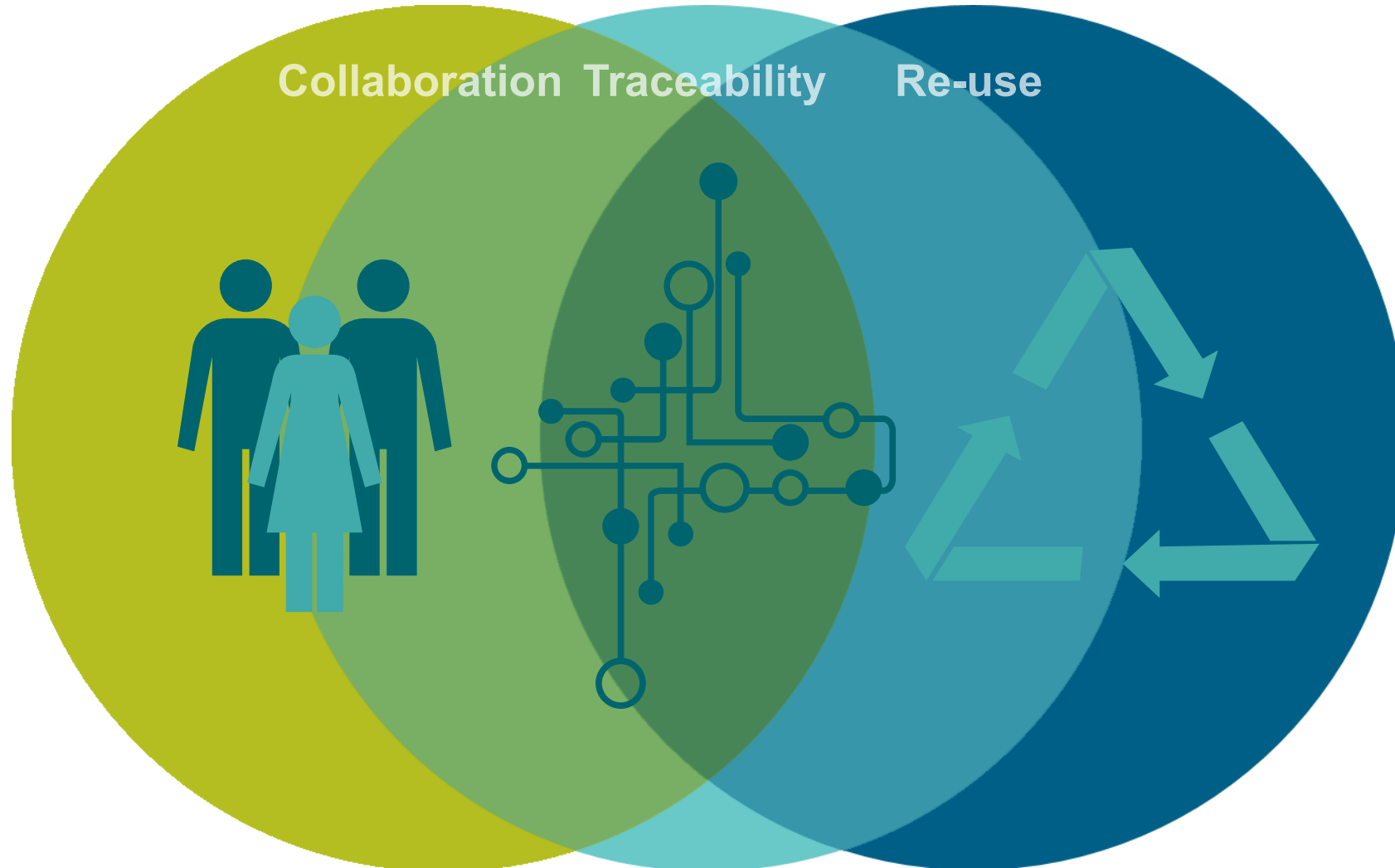
## Traceability



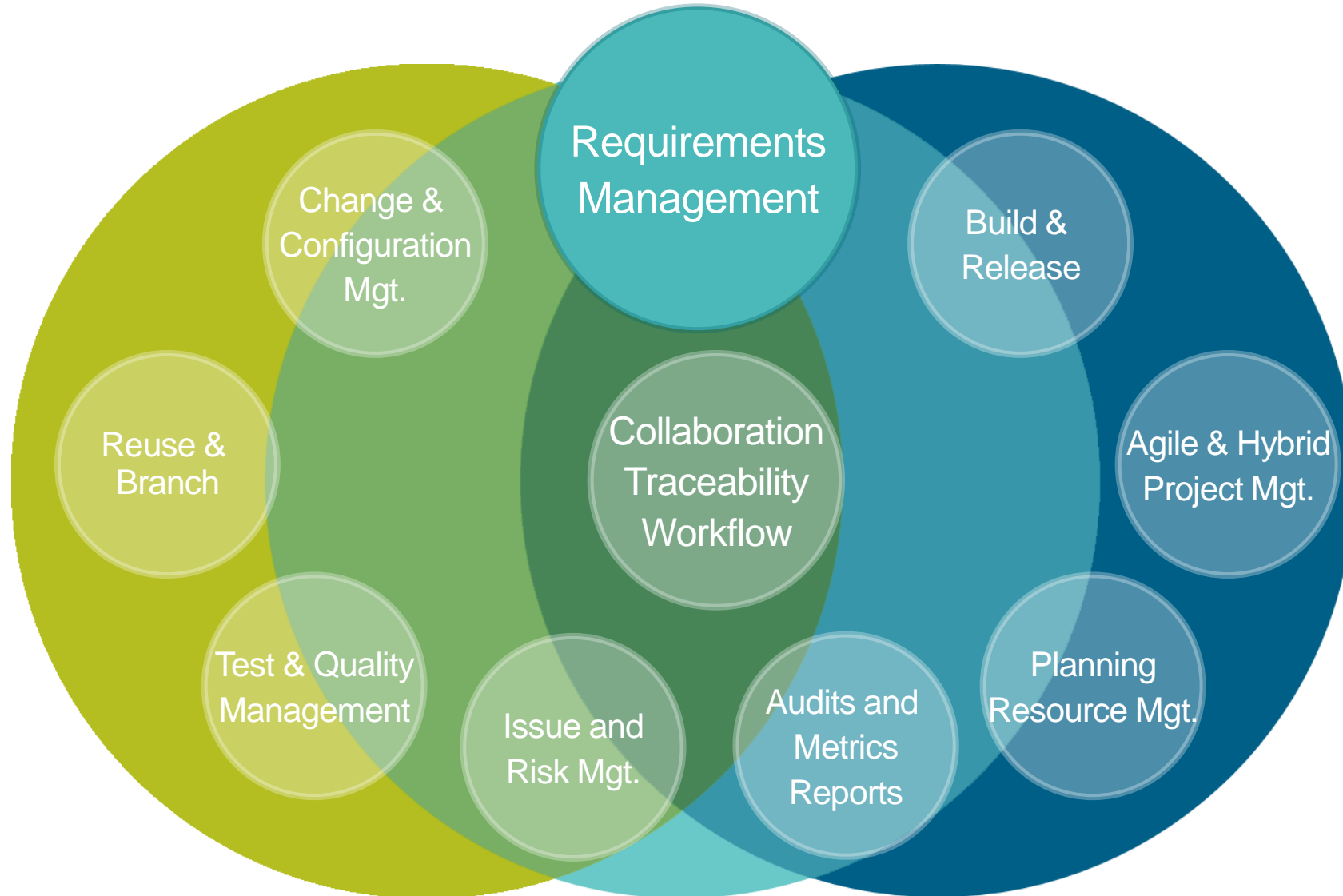
## Re-use



# The boundaries between pillars are disappearing







# Existing specification documents

**3 Requirements**

**3.1 General State**

The car should have approximately following Dimensions:

Dimension	Interval
width	2000-2300 mm
length	4200-4300 mm
height	1100-1200 mm

The car must have alloy wheels with minimum 20 inch for a sporty look.

**3.2 Range**

The car must have a range of minimum 500km with a battery charge.

**3.3 Engine**

The car must have an electric engine with following properties:

- The electric engine must provide at least 700ps.
- V-Max should be more than 300 km/h.
- The weight should not be more than 200 kg.

**3.4 Brakes**

It must be possible to operate the kers-system with the used breaking technology.

The brake calipers should be visible and painted in Polarion-Blue.

The brakes should look sporty.

**3 Requirements**

**3.1 General State**

**MRM-557** - The car should have approximately following Dimensions:

Dimension	Interval
width	2000-2300 mm
length	4200-4300 mm
height	1100-1200 mm

Should Have, Reviewed

**MRM-558** - The car must have alloy wheels with minimum 20 inch for a sporty look. Must Have, Reviewed

**3.2 Range**

**MRM-560** - The car must have a range of minimum 500km with a battery charge. Must Have, Reviewed

**3.3 Engine**

**MRM-562** - The car must have an electric engine with following properties: Must Have, Reviewed

**MRM-563** - The electric engine must provide at least 700ps. Must Have, Reviewed

**MRM-564** - V-Max should be more than 300 km/h. Should Have, Reviewed

**MRM-565** - The weight should not be more than 200 kg. Should Have, Reviewed

**3.4 Brakes**

**MRM-567** - It must be possible to operate the kers-system with the used breaking technology. Must Have, Reviewed

**MRM-568** - The brake calipers should be visible and painted in Polarion-Blue. Should Have, Reviewed

**MRM-569** - The brakes should look sporty. Should Have, Reviewed

# Documents & Individual requirements

**3 Requirements**

**3.1 General State**

**MRM-557** - The car should have approximately following Dimensions:

Dimension	Interval
width	2000-2300 mm
length	4200-4300 mm
height	1100-1200 mm

Should Have, Reviewed

**MRM-558** - The car must have alloy wheels with minimum 20 inch for a sporty look.

Must Have, Reviewed

**3.2 Range**

**MRM-560** - The car must have a range of minimum 500km with a battery charge.

Must Have, Reviewed

**3.3 Engine**

**MRM-562** - The car must have an electric engine with following properties:

**MRM-563** - The electric engine must provide at least 700ps.

Must Have, Reviewed

**MRM-564** - V-Max should be more than 300 km/h.

Must Have, Reviewed

**MRM-565** - The weight should not be more than 200 kg.

Should Have, Reviewed

**3.4 Brakes**

**MRM-567** - It must be possible to operate the kers-system with the used breaking technology.

Must Have, Reviewed

**MRM-568** - The brake calipers should be visible and painted in Polarion-Blue.

Should Have, Reviewed

**MRM-569** - The brakes should look sporty.

Should Have, Reviewed



**3.3 Engine**

**MRM-645** - The car must have an electric engine with following properties:

Must Have, Draft

**MRM-646** - The electric engine must provide at least 700ps.

Must Have, Draft

**MRM-647** - V-Max should be more than 300 km/h.

Should Have, Draft

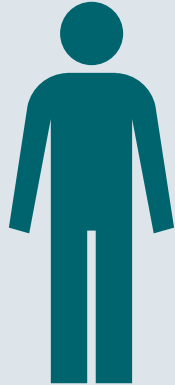
**MRM-648** - The weight should not be more than 200 kg.

Should Have, Draft

```

    graph LR
      Start(( )) --> Draft[Draft]
      Draft --> InReview[In Review]
      InReview --> Approved[Approved]
      Approved --> Accepted[Accepted]
  
```

# External stakeholders




## Internal stakeholders


### 3 Requirements

#### 3.1 General State


**MRM-640** - The car should have approximately following Dimensions:

Dimension	Interval
width	2000-2300 mm
length	4200-4300 mm
height	1100-1200 mm


Should Have 


**MRM-641** - The car must have alloy wheels with minimum 20 inch for a sporty look.  Must Have 


#### 3.2 Range


**MRM-643** - The car must have a range of minimum 500km with a battery charge.  Must Have 


#### 3.3 Engine


**MRM-645** - The car must have an electric engine with following properties.  Must Have 

**MRM-646** - The electric engine must provide at least 700ps.  Must Have 

**MRM-647** - V-Max should be more than 300 km/h.  Should Have 

**MRM-648** - The weight should not be more than 200 kg.  Should Have 


**MRM-641** - The car must have alloy wheels with minimum 20 inch for a sporty look  .

Will not Have  Draft

I'm not sure about the minimum size!!




## External stakeholders



### 3.1 General State


**MRM-640** - The car should have approximately following Dimensions:

Dimension	Interval
width	2000-2300 mm
length	4200-4300 mm
height	1100-1200 mm

Should Have 

**MRM-641** - The car must have alloy wheels with minimum 20 inch for a sporty look.  Must Have 

### 3.3 Engine

**MRM-645** - The car must have an electric engine with following properties:  Must Have 



# Traceability

**3.5 Battery**

Following battery requirements are recommended:

- MRM-571** - The battery should hold 4000 charge cycles. Should Have, Reviewed
- MRM-572** - The battery should be delivered by one of our partners. Should Have, Reviewed
- MRM-573** - The battery should not be more than 20% from the entire vehicle weight. Should Have, Reviewed
- MRM-574** - The battery must have a connection to a kers-system. Must Have, Reviewed
- MRM-575** - Following battery properties should be respected:

Property	Share
Volt	650
Ampere	300
Size	15

**3.6 Inner space**

Remember to save the [Document](#) when you finish linking.

**Linked with MRM-571** ✓

from Mo1 RM > Automotive\_PolarCar\_Specifications

is verified by MRM-666

**Test Case Specification**

- MRM-666** - The battery should hold 4000 charge cycles Draft
- MRM-664** - Th battery should be delivered by one of our partners Draft
- MRM-665** - The battery should not be more than 20% from the entire vehicle weight Draft
- MRM-667** - The battery must have a connection to a kers-system Draft

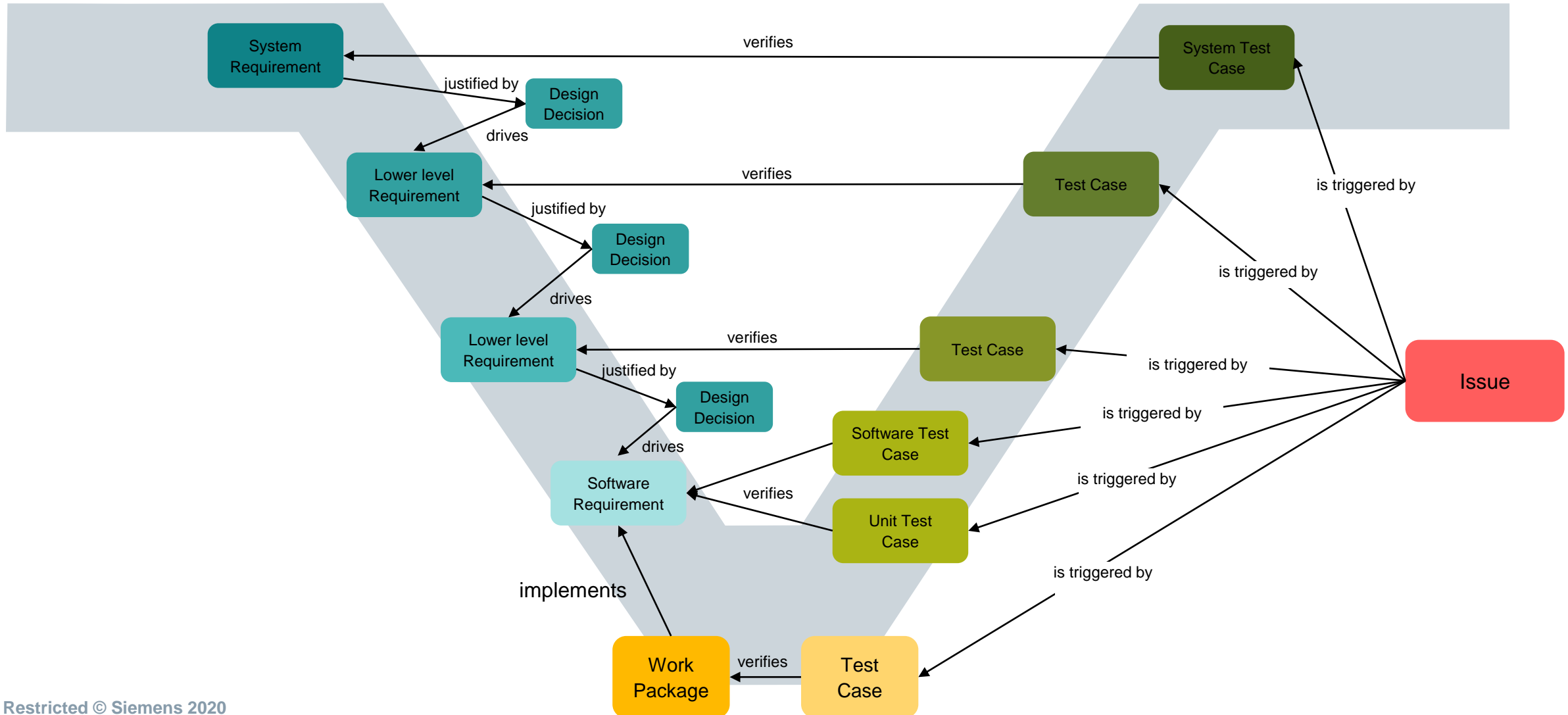
Remember to save the [Document](#) when you finish linking.

**Linked with MRM-571** ✓

from Mo1 RM > Automotive\_PolarCar\_Specifications

is verified by MRM-666

# Polarion linking model - Example



# Traceability & Coverage

Rows: Work Items ▼ Typ

Columns: Work Items ▼ Typ

Save Revert Refresh

- MD MMDP-8444 - The device will egress EO ga
- MD MMDP-8443 - EO Gas and steam humidity
- SM MMDP-8441 - Device will be EO sterilized p
- MD MMDP-8403 - Design will permit escape of f
- MD MMDP-6262 - The CPU will not exceed a te
- MD MMDP-5543 - ISO 11607 Compliance
- MD MMDP-5542 - The gas ingress material will
- MD MMDP-5541 - The sterile barrier bag will inc
- MD MMDP-4810 - The device will withstand a dr

## Requirement Test Case Coverage

	Requirement	Test Case(s)	Issue(s)	Details
✗	MRM-313 - DrivePilot shall easily engage operations while the vehicle is at rest.			No Test Case(s) Found.
✗	MRM-314 - DrivePilot may not be engaged while the vehicle is under manual control.* provid...			No Test Case(s) Found.
✗	MRM-315 - DrivePilot shall be easy to operate without extensive training.			No Test Case(s) Found.
✓	MRM-316 - Before any user may engage DrivePilot on public roads, that user must successful...			▼ 1 Test Case Found
	MRM-224 - A tutorial is required before the first run.		MRM-449 - Failed: A tutorial is required before the first run.. ▶	
✓	MRM-317 - Drive Pilot warnings on special conditions			▼ 2 Test Cases Found
	MRM-473 - DrivePilot will disengage when User shouts "Stop"		MRM-475 - Failed: DrivePilot will disengage when User shouts "Stop" ▶	
	MRM-474 - DrivePilot will disengage when Brake is manually engaged			
✗	MRM-322 - DrivePilot controls accelerator/throttle with software-based control commands an...			No Test Case(s) Found.
✗	MRM-323 - The DrivePilot user console shall have common views in the built-in displays, an...			No Test Case(s) Found.
✗	MRM-324 - The DrivePilot user console will operate in the following platforms:			No Test Case(s) Found.
✗	MRM-330 - The DCC shall conform to existing best practices for ARM processor circuit board...			No Test Case(s) Found.
✓	MRM-331 - The DCC will operate on 4.3 Volts, 500mA with a variance tolerance of +/- 10%. P...			▼ 2 Test Cases Found
	MRM-333 - Check circuit protector fuses is triggered on power outside of tolerance (600mA).			
	MRM-335 - Check circuit protector fuses is triggered on power outside of tolerance (5v).			
✓	MRM-332 - DrivePilot is NOT compatible with any vehicle that has "auto parking" capability...			▼ 1 Test Case Found
	MRM-472 - DrivePilot cannot be started on vehicles with "auto-parking"			
✗	MRM-334 - The User Console will resemble a typical dashboard display and include options f...			No Test Case(s) Found.

Target Version  
-- not selected --

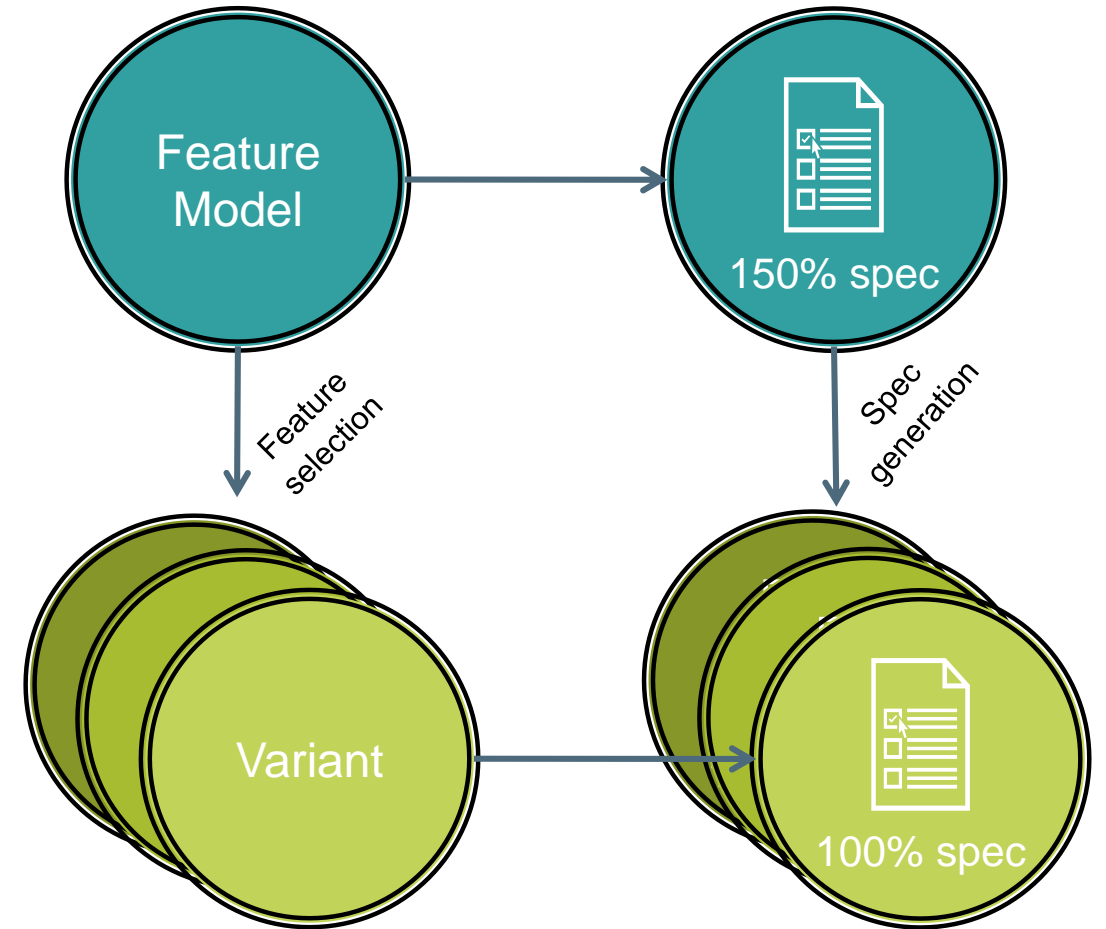
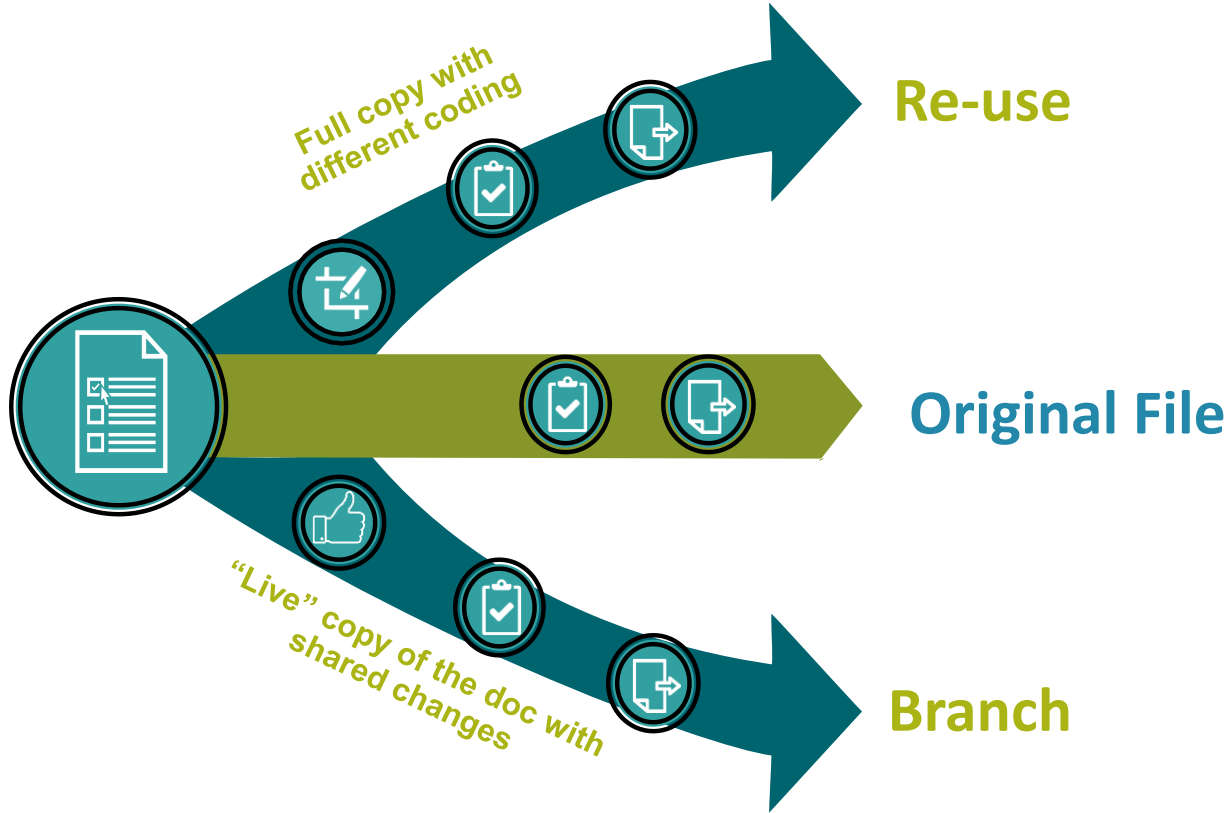
Requirement Query

Filter Linked Items By Coverage  
-- not selected --

Collapse from number of Work Packages

Apply [Save as Default](#)

# Re-use







Setup



D(r)efine



Review



Import



Use

Collaborate

Ensure traceability

Effective reuse

# Agenda



- Introduction
- Vision Siemens Digital Industries Software (Piet)
- Digitalization of Systems Engineering (Stefan)
- Requirement Management with Polarion (Marco)

# Q&A

**Thank you.**